

research report

Inelastic Lateral-Torsional Buckling Strength Validation for Non-Principal Axis Bending Using Numerical Methods

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for the Design of Cold-Formed
Steel Structural Members



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Abstract

The current design specification for point-symmetric cold-formed steel members in North America (AISI S100) has long applied a conservative simplification for elastic lateral-torsional buckling. This report aims to provide additional validation of a recently proposed design approach. The validation involves a series of numerical analyses designed to assess the accuracy of proposed changes for lateral-torsional buckling behavior of point-symmetric section bent about a non-principal axis. Using a set of 14 lipped Zee sections with sharp corners, numerical analysis was carried out for elastic buckling using the finite strip method, and shell finite element method, and in addition inelastic shell finite element collapse analysis was conducted to determine the expected strength. As reference, analytical equations from previous research (Glauz, 2017) are also used to validate the elastic lateral-torsional buckling simulations. Nominal flexural capacity was predicted by three design methods: AISI S100-16 approximate approach, AISI S100-16 linear interaction approach, and a new method considering direct bi-axial bending. The simulation results are compared with the proposed provisions for both stability and strength determination. The level of conservatism in the strength predictions is high for the selected members based on the assessment of the data, especially for those members with higher global slenderness. The assessment in this report focused primarily on the global inelastic buckling range, where it was found that the method considering direct bi-axial bending is preferred.

1 Introduction

This project was conducted as part of a fellowship supported by the American Iron and Steel Institute (AISI). The project fellowship application well describes the current state of the art in lateral-torsional buckling of general open cold-formed steel cross-sections when loaded about non-principal axes and is directly quoted here to provide an efficient introduction:

“Current AISI provisions for lateral-torsional buckling of non-symmetric cold-formed steel members can be overly conservative. The Specification [AISI S100] has long taken a simplistic approach to lateral-torsional buckling provisions for non-symmetric members – and these provisions are particularly problematic when the bracing and the principal axes of the section do not align. Such bracing conditions are common since the bracing tends to follow the overall structural layout (struts or straps from frame/roof lines, rack uprights and beams, etc.) while the member section has principal axes that are inclined to the structural layout. Non-symmetric members can potentially serve as efficient purlins, girts, joists, rack uprights, etc. as they allow the section to be optimized for shipping, unequal bending demands, and other unique conditions. The future application of efficient cross-sections in cold-formed steel structural systems relies on accurate provisions for predicting the strength in these conditions.

AISI ballot S17-438A introduced provisions for determining the lateral-torsional elastic buckling stress for non-symmetric sections bending about non-principal axes. This ballot received a high response and approval rate, but one negative vote prevented the ballot from passing. Although the determination of elastic buckling stress was well supported, the remainder of the bending strength provisions in the Specification were insufficient for non-principal axes.

A proposed method of handling biaxial bending strength was presented to members of Subcommittee 24 on Member Design in July 2017, with validation against a small set of physical test data. The objective of this project is to provide additional validation of the proposed design approach. Since the available set of physical test data is limited, this project will involve numerical analysis for validation.

The sections and analysis parameters used in this study will be strategically chosen to reflect representative and sufficient cases to validate the method, but with the objective of reducing the analysis effort. Upon completion of this work, a revised ballot S17-438B will be prepared for approval by Subcommittee 24.”

Non-symmetric members can potentially serve as efficient purlins, girts, joists, rack uprights, etc. Unlike conventional singly-symmetric cold-formed steel members, the support layout and the principal axes do not align for such members. For example, the common Zee-shaped sections have principal axes inclined from the web and flange as shown in Fig. 1. As a result of the location of the principal axis common gravity loading (for example in the -Y direction of Fig.1) causes bending about both principal axes - which leads to difficulty in determining the critical elastic lateral-torsional buckling stress. Analytical formula for the elastic lateral-torsional (global) buckling for bending about any inclined axis from the major principal axis has recently been developed by Glauz (2017) and serves as motivation for this study.

In addition to the geometric (X-Y) and principal (1-2) axes Fig. 1 depicts another set of arbitrary axes (a-b) which are an angle θ from the principal major axis, and an angle β from geometric axis. In the work herein, we will consider bending about the arbitrary axis “a” and the resulting global elastic buckling and strength. As depicted in Fig. 2 and Fig. 3 bending about axis “a” may result from directly applied loads (W_a) or moments (M_a) – regardless such actions may be decomposed back into the principal axes (1 and 2) or considered directly in the axes of bending (a). Considering the classic case of end moment, M_a , may be expressed as stress at the end of the member as shown in Fig. 4. This report considers the elastic buckling, inelastic buckling, and ultimate strength of typical Zee-shaped cold-formed steel members under the end stress of Fig. 4 developed from end moment M_a . As discussed herein, members and details are selected to focus on global lateral-torsional buckling, not local or distortional buckling.

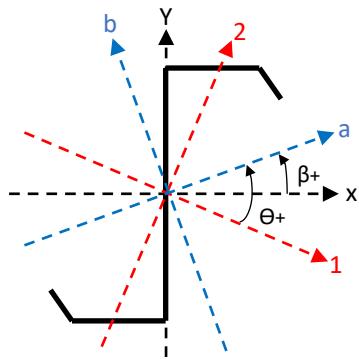


Figure 1. Geometric (X-Y), principal (1-2), and arbitrary (a-b) coordinate axes.

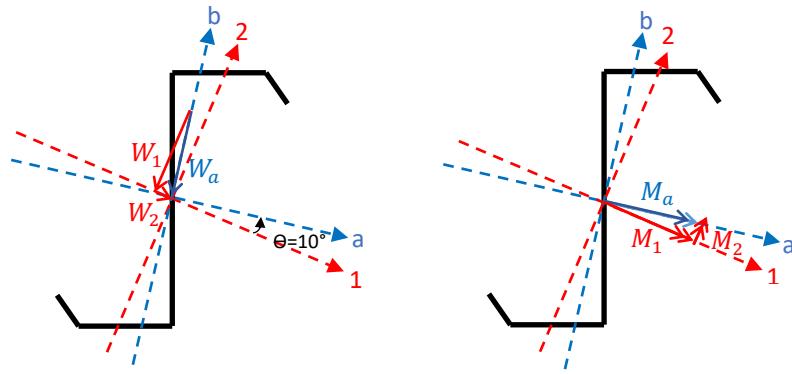


Figure 2. Decomposition of force (W_a) and end moment (M_a) for $\theta = 10^\circ$.

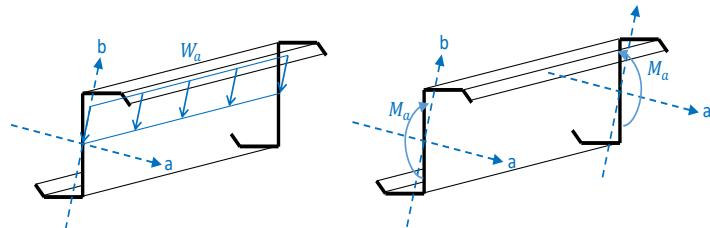


Figure 3. Example member loading for force and applied end moments at $\theta = 10^\circ$.

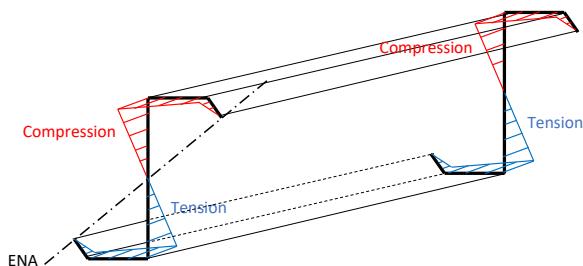


Figure 4. Equivalent end stress for applied end moment example at $\theta = 10^\circ$.

2 Selected Cross-sections

Fourteen lipped Zee sections are selected based on Glauz (2017). AISI-D100 is used as the reference to identify section dimensions for the studied members. A centerline model is used for calculating the torsional properties. In addition, it is assumed that the corners are sharp. The reason for using the sharp corner in the analytical approximations and models is to avoid additional disagreement between analytical solutions which require torsion property, C_w , (and traditionally use sharp corners) and numerical solutions which do not require sharp corners and thus focus any differences on behavior – not the calculation method. CUFSM is used for generating the section models and the section properties are verified with the AISI-D100 cross-section tables. The section dimensions are shown in Table 1.

Table 1. Sharp corner Zee section dimensions for CUFSM input.

ID	dimensions						
	D in.	B in.	t in.	d in.	γ deg	R in.	Area in.^2
12ZS3.25×105	12.000	3.250	0.105	0.990	50	0	2.118
12ZS2.75×105	12.000	2.750	0.105	0.990	50	0	2.013
12ZS2.25×105	12.000	2.250	0.105	0.990	50	0	1.908
10ZS3.25×105	10.000	3.250	0.105	0.990	50	0	1.908
10ZS2.75×105	10.000	2.750	0.105	0.990	50	0	1.803
10ZS2.25×105	10.000	2.250	0.105	0.990	50	0	1.698
9ZS2.25×105	9.000	2.250	0.105	0.990	50	0	1.593
8ZS3.25×105	8.000	3.250	0.105	0.990	50	0	1.698
8ZS2.75×105	8.000	2.750	0.105	0.990	50	0	1.593
8ZS2.25×105	8.000	2.250	0.105	0.990	50	0	1.488
7ZS2.25×105	7.000	2.250	0.105	0.990	50	0	1.383
6ZS2.25×105	6.000	2.250	0.105	0.990	50	0	1.278
4ZS2.25×70	4.000	2.250	0.070	0.930	50	0	0.711
3.5ZS1.5×70	3.500	1.500	0.070	0.680	50	0	0.536

3 Cross-section Properties

To insure that the selected cross-sections were being transferred to software correctly and to understand the impact of different modeling assumptions cross-section properties for the selected Z-sections were calculated by hand, and in models created with the programs CFS (version 11) and CUFSM (version 5.03).

Table 2. Sharp corner Zee section properties from CUFSM.

ID	Properties of Full Section												
	Axis x-x			Axis y-y			I_{xy}	I_{x2}	I_{y2}	r_{min}	α	J	C_w
	I_x	S_x	r_x	I_y	S_y	r_y							
	in.^4	in.^3	in.	in.^4	in.^3	in.	in.^4	in.^4	in.^4	in.	deg	in.^4	in.^6
12ZS3.25×105	44.614	7.436	4.589	4.703	1.210	1.490	10.219	2.239	47.078	1.028	76.442	0.008	122.563
12ZS2.75×105	40.900	6.817	4.507	3.148	0.930	1.251	7.828	1.589	42.459	0.888	78.738	0.007	85.085
12ZS2.25×105	37.186	6.198	4.415	1.975	0.684	1.017	5.750	1.060	38.101	0.745	80.957	0.007	55.513
10ZS3.25×105	29.046	5.809	3.902	4.703	1.210	1.570	8.456	2.054	31.695	1.038	72.606	0.007	81.836
10ZS2.75×105	26.476	5.295	3.832	3.148	0.930	1.321	6.473	1.472	28.151	0.904	75.486	0.007	57.000
10ZS2.25×105	23.905	4.781	3.752	1.975	0.684	1.079	4.750	0.990	24.890	0.764	78.289	0.006	37.333
9ZS2.25×105	18.565	4.126	3.414	1.975	0.684	1.113	4.251	0.950	19.591	0.772	76.434	0.006	29.668
8ZS3.25×105	17.294	4.323	3.191	4.703	1.210	1.664	6.692	1.811	20.186	1.033	66.625	0.006	49.874
8ZS2.75×105	15.658	3.914	3.135	3.148	0.930	1.406	5.118	1.321	17.485	0.911	70.354	0.006	34.870
8ZS2.25×105	14.021	3.505	3.070	1.975	0.684	1.152	3.751	0.903	15.093	0.779	74.044	0.005	22.942
7ZS2.25×105	10.222	2.920	2.719	1.975	0.684	1.195	3.251	0.848	11.349	0.783	70.872	0.005	17.143
6ZS2.25×105	7.114	2.371	2.359	1.975	0.684	1.243	2.752	0.780	8.309	0.781	66.518	0.005	12.259
4ZS2.25×70	1.882	0.941	1.627	1.294	0.454	1.349	1.175	0.376	2.799	0.728	52.012	0.001	3.383
3.5ZS1.5×70	1.032	0.590	1.388	0.400	0.206	0.864	0.476	0.145	1.287	0.520	61.799	0.001	0.830

Table 3. Percent difference between CUFSM model and D-100 tables.

ID'	Properties of Full Section												
	Axis x-x			Axis y-y			I_{xy}	I_{x2}	I_{y2}	r_{min}	α	J	C_w
	I_x	S_x	r_x	I_y	S_y	r_y							
	in.^4	in.^3	in.	in.^4	in.^3	in.	in.^4	in.^4	in.^4	in.	deg	in.^4	in.^6
12ZS3.25×105	2.09%	2.00%	0.43%	0.70%	-0.81%	0.01%	0.19%	2.69%	1.90%	0.79%	0.19%	1.22%	-0.36%
12ZS2.75×105	2.25%	2.20%	0.39%	0.58%	-0.89%	0.04%	0.62%	2.53%	2.06%	0.62%	0.18%	1.20%	-0.02%
12ZS2.25×105	2.44%	2.44%	0.56%	0.78%	-1.11%	-0.25%	0.69%	2.92%	2.42%	0.59%	0.19%	1.33%	0.02%
10ZS3.25×105	2.27%	2.09%	0.30%	0.70%	-0.81%	-0.64%	0.54%	2.71%	1.91%	0.73%	0.28%	1.33%	0.04%
10ZS2.75×105	2.22%	2.42%	0.57%	0.58%	-0.89%	-0.65%	0.51%	2.96%	2.00%	0.74%	0.38%	1.32%	0.00%
10ZS2.25×105	2.60%	2.60%	0.59%	0.78%	-1.11%	-0.14%	0.64%	2.96%	2.43%	0.76%	0.24%	1.47%	0.09%
9ZS2.25×105	2.57%	2.63%	0.70%	0.78%	-1.11%	-0.58%	0.72%	3.21%	2.57%	0.79%	0.31%	1.64%	-0.11%
8ZS3.25×105	2.33%	2.21%	0.35%	0.70%	-0.81%	-0.35%	0.48%	3.46%	1.95%	1.23%	0.49%	1.47%	-0.05%
8ZS2.75×105	2.34%	2.47%	0.48%	0.58%	-0.89%	-0.30%	0.55%	3.20%	2.25%	0.95%	0.51%	1.64%	-0.09%
8ZS2.25×105	3.10%	2.80%	0.64%	0.78%	-1.11%	-0.68%	0.56%	3.52%	2.67%	0.89%	0.47%	1.65%	0.18%
7ZS2.25×105	3.04%	3.20%	0.69%	0.78%	-1.11%	-0.41%	0.66%	4.00%	2.25%	1.14%	0.53%	1.86%	0.25%

6ZS2.25×105	3.24%	3.09%	0.39%	0.78%	-1.11%	-0.55%	0.79%	4.67%	2.45%	1.31%	0.79%	1.89%	-0.33%
4ZS2.25×70	3.38%	3.38%	0.43%	1.12%	-0.55%	-0.78%	0.46%	6.00%	1.80%	1.90%	0.99%	1.84%	0.09%
3.5ZS1.5×70	4.79%	4.77%	0.57%	0.99%	-0.74%	-0.92%	0.82%	8.04%	2.99%	2.32%	1.31%	2.96%	-0.01%

Table 2 shows the cross-section properties for Zees from CUFSM, and Table 3 shows the comparison from software results to the AISI-D100 reference. Larger differences exist for other properties (I , etc.) because D100-17 uses rounded corners for them (note if round corner models are created in CUFSM and CFS agreement is nearly exact – but then C_w agreement is poor). Small differences exist for C_w because D100-17 uses the sharp corner formulas for C_w , which supports the sections use to calculate the buckling moment resistance of lateral unbraced beams and torsional-flexural buckling of compression members.

4 Elastic Lateral-torsional Buckling Calculations

Elastic lateral-torsional buckling (LTB) for bending about an axis not aligned with the major principal axis is an unusual case, not traditionally included in classical derivations or design specifications. However, Glauz (2017) provided a clear derivation for the solution using classical bifurcation theory and therefore today analytical and numerical solutions both exist for this case. For the studied sections under a variety of different bending axes the elastic LTB moment M_{cre} was calculated per Glauz (2017), CFS, CUFSM, and in ABAQUS (with shell elements) and compared in Table 4.

Table 4. Buckling moment under unrestrained bending about geometric axis (X of Fig. 1) for sharp corner Zee sections with $F_y = 50$ ksi and $L = 180$ in.

ID	Analytical M_{cre}		FSM M_{cre}		ABAQUS M_{cre}
	CUFSM ¹	CFS ¹	CUFSM	CFS	
	kip-in	kip-in	kip-in	kip-in	kip-in
12ZS3.25×105	158.891	158.407	157.627	157.330	157.320
12ZS2.75×105	112.134	111.807	111.509	111.270	111.336
12ZS2.25×105	75.119	74.922	74.860	74.749	74.774
10ZS3.25×105	128.093	127.655	127.429	127.060	127.157
10ZS2.75×105	90.878	90.575	90.565	90.346	90.407
10ZS2.25×105	61.340	61.133	61.224	61.080	61.142
9ZS2.25×105	54.739	54.537	54.669	54.530	54.588
8ZS3.25×105	99.246	98.850	98.921	98.590	98.685
8ZS2.75×105	70.927	70.643	70.793	70.565	70.651
8ZS2.25×105	48.373	48.180	48.337	48.204	48.259
7ZS2.25×105	42.291	42.105	42.280	42.149	42.202
6ZS2.25×105	36.553	36.371	36.560	36.426	36.483
4ZS2.25×70	14.799	14.733	14.800	14.746	14.771
3.5ZS1.5×70	5.306	5.277	5.317	5.292	5.310

1. Analytical formula of Glauz (2017) with cross-section properties generated from sharp corner model created in CUFSM or CFS as noted.

In Table 4, the values for Analytical M_{cre} were calculated using the analytical formula from Glauz (2017) for point-symmetric sections with properties that came from CUFSM and CFS. FSM M_{cre} values were directly determined using the finite strip method in CUFSM and CFS. ABAQUS M_{cre} values were determined from shell finite element models with stress at the ends and using elastic eigenvalue buckling analysis.

Based on the results from Table 4, the buckling moment conducted by the different methods match closely. This verifies that the elastic LTB buckling calculation for bending about non-principal axis is robust and can be performed by any of the selected methods with confidence.

5 Shell FE Collapse Analysis

5.1 Model setup

Unbraced cold-formed steel beams are prone to lateral-torsional buckling when the compression flange is not restrained by sheathing or other bracing. Our objective is to isolate the failure mode of lateral-torsional buckling and yielding (from local and distortional buckling) and interrogate this limit state through shell finite element collapse analysis in ABAQUS. We selected the 6ZS2.25×105 as the first section since this is the least likely to incur local or distortional buckling. The S9R5 shell finite element is selected with a dense mesh of 20-8-8 elements for the web-flange-lip. Elastic perfectly-plastic is selected for the material model. The member boundary conditions for the beam end is restrained perpendicular to the web, and perpendicular to the flange, and for the middle cross-section is restrained in the longitudinal direction.

The basic analysis is conducted in two parts: apply a reference moment equal to the yielding strength with different unbraced length ($L = 144$ in., 180 in., and 240 in.), and include different yielding strengths ($F_y = 33$ ksi, 40 ksi, and 50 ksi) with the same unbraced length ($L = 144$ in.). A total of five cases were evaluated for each section. The loading moment applied on the bending axes “a”, rotated θ from the principal axis, is decomposed into major and minor principal axes demands, a sample loading summary is shown in Table 5.

Table 5. Applied bending moment decomposition vary with inclined bending axes.

θ (degree)	M_{ref}	M_1	M_2
	kip-in	kip-in	kip-in
transition angle	-8	55.646	55.105
	-4	55.646	55.511
principal-major	0	55.646	55.646
	4	55.646	55.511
transition angle	8	55.646	55.105
	12	55.646	54.430
geometric	16	55.646	53.491
	20	55.646	52.291
principal-minor	23.481	55.646	51.039
	90	55.646	0.000
			-55.646

In the ABAQUS modeling, for the nonlinear collapse analysis, the RIKS solver is employed for equilibrium convergence.

Note, no initial imperfections are considered in the initial collapse analysis. For any moment about non-principal axes there is always first order deformation in both principal axes – thus for global LTB the role of imperfections is less important. This report does examine imperfection sensitivity after the primary studies are provided, later in this report.

5.2 Typical Result

The moment about any rotated axes “a” generates a new stress distribution (Fig. 4). CUFSM, consistent with Ugural and Fenster (2003) provides the generalized flexural stress as function of applied moments as:

$$\sigma_x = \frac{(M_y I_x + M_x I_{xy})x - (M_y I_{xy} + M_x I_y)y}{I_x I_y - I_{xy}^2} \quad (1)$$

Where M_x and M_y are components of the moment about the axis of bending M_a .

The 6ZS2.25×105 section with $F_y = 50$ ksi and $L=144$ inches is selected for showing typical analysis results. The bending moment is applied about the geometric axis ($\theta = 23.481^\circ$). Fig. 5 shows the end stress distribution. In ABAQUS the displacement in Y (perpendicular to the web) and Z (perpendicular to the flange) direction is taken as the average value between the upper and lower web-flange junction. The web twist angle was calculated by trigonometric function using the displacement at the two web-flange junctions and the web height. The boundary condition for the two ends are restrained in the y- and z-direction (ABAQUS coordinate system), while for the middle is restrained only in the x-direction.

Fig. 6 to Fig. 8 provide the finite element model buckling shape with specific loading and boundary conditions, while Fig. 9 provides the moment-deformation plots for collapse analysis with unrestrained bending about geometric axis of 6ZS2.25×105 with $F_y = 50$ ksi and $L = 144$ in ($\theta=23.481^\circ$). As the figures indicate the section experiences primary deformations (Z-direction in the ABAQUS model) as well as lateral deformations (Y-direction in the ABAQUS model) and twist. At peak moment neither local or distortional deformations are present – indicating that the section successfully isolates lateral-torsional buckling and yielding. In collapse spatial mechanisms form shown as yielded zones in the stress contours and falling moment capacity in the moment-deformation plots.

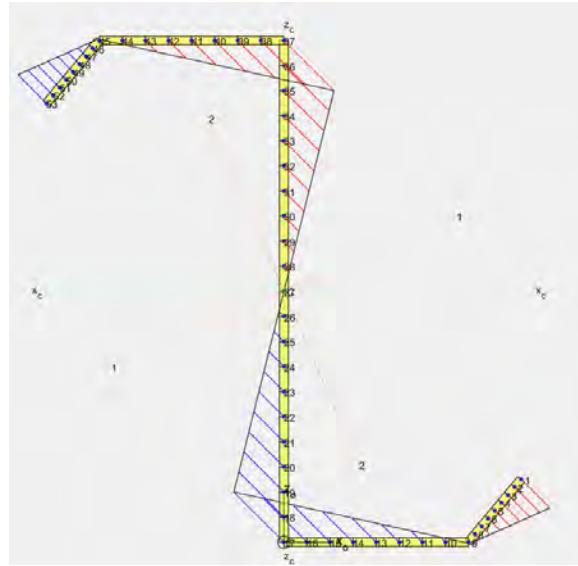


Figure 5. End stress distribution for 6ZS2.25×105 section with $F_y = 50$ ksi and $L=144$ in.
 $(\theta=23.481^\circ)$.

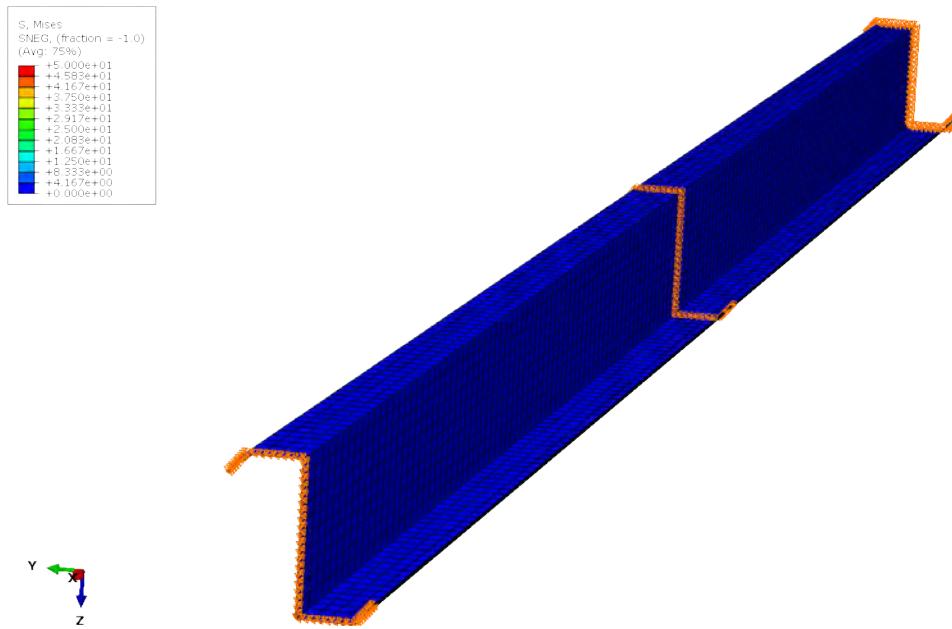


Figure 6. Selected member with no load at initial stage.

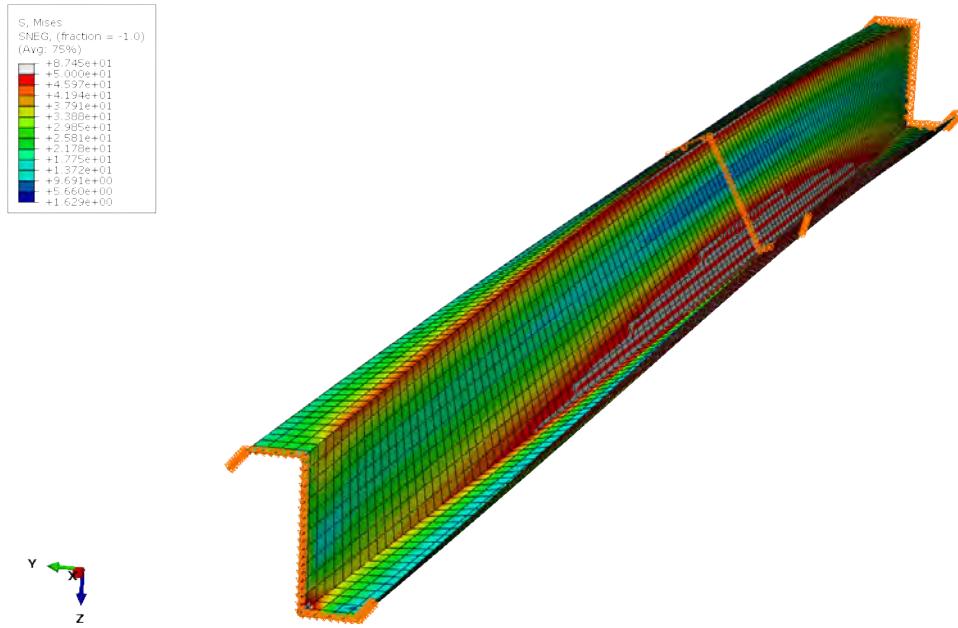


Figure 7. Deformed shape at the peak moment.

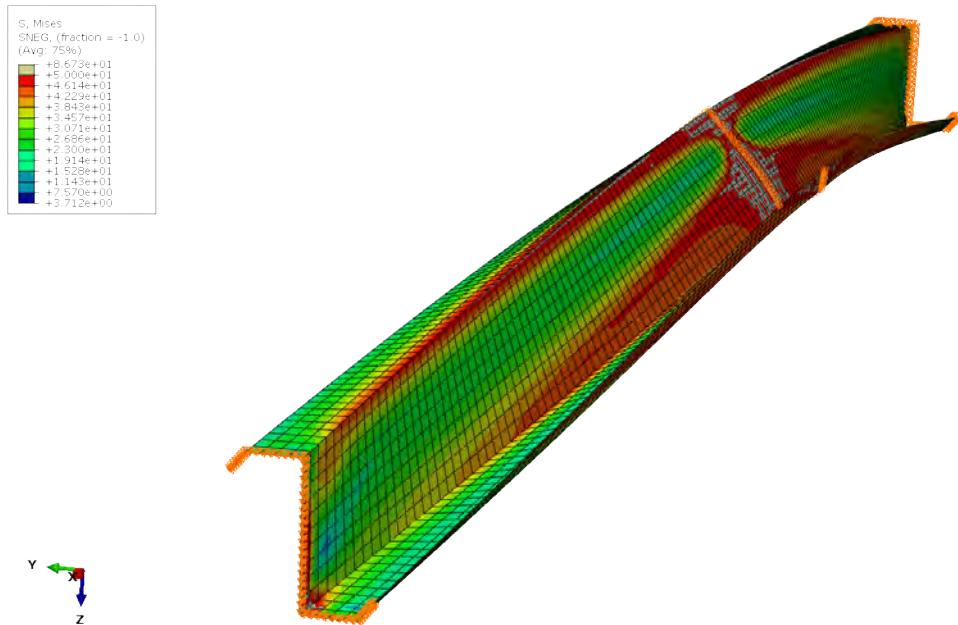


Figure 8. Deformed shape at the end of simulation.

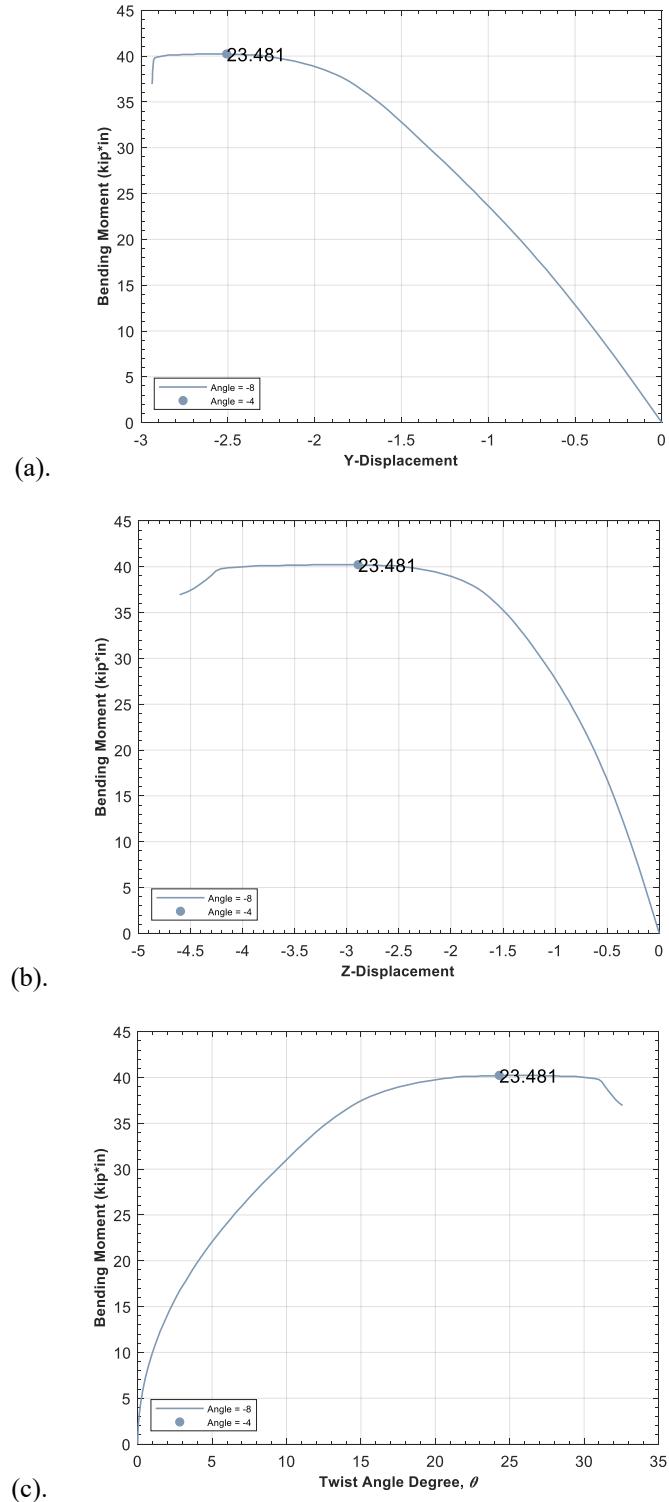


Figure 9. Moment-deformation plots for 6ZS2.25×105 with $F_y = 50$ ksi and $L = 144$ in at $\theta = 23.481^\circ$. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

5.3 Studied Cases

Table 6. Studied cases in this report.

Section	Fy (ksi)	L (in)	θ (degree)	Section	Fy (ksi)	L (in)	θ (degree)
6ZS2.25×105	33	144	-8	10ZS2.25×105	33	144	-8
6ZS2.25×105	33	144	-4	10ZS2.25×105	33	144	-4
6ZS2.25×105	33	144	0	10ZS2.25×105	33	144	0
6ZS2.25×105	33	144	4	10ZS2.25×105	33	144	4
6ZS2.25×105	33	144	8	10ZS2.25×105	33	144	8
6ZS2.25×105	33	144	12	10ZS2.25×105	33	144	11.711
6ZS2.25×105	33	144	16	10ZS2.25×105	33	144	12
6ZS2.25×105	33	144	20	10ZS2.25×105	33	144	16
6ZS2.25×105	33	144	23.481	10ZS2.25×105	33	144	20
6ZS2.25×105	33	144	90	10ZS2.25×105	33	144	90
6ZS2.25×105	40	144	-8	10ZS2.25×105	40	144	-8
6ZS2.25×105	40	144	-4	10ZS2.25×105	40	144	-4
6ZS2.25×105	40	144	0	10ZS2.25×105	40	144	0
6ZS2.25×105	40	144	4	10ZS2.25×105	40	144	4
6ZS2.25×105	40	144	8	10ZS2.25×105	40	144	8
6ZS2.25×105	40	144	12	10ZS2.25×105	40	144	11.711
6ZS2.25×105	40	144	16	10ZS2.25×105	40	144	12
6ZS2.25×105	40	144	20	10ZS2.25×105	40	144	16
6ZS2.25×105	40	144	23.481	10ZS2.25×105	40	144	20
6ZS2.25×105	40	144	90	10ZS2.25×105	40	144	90
6ZS2.25×105	50	144	-8	10ZS2.25×105	50	144	-8
6ZS2.25×105	50	144	-4	10ZS2.25×105	50	144	-4
6ZS2.25×105	50	144	0	10ZS2.25×105	50	144	0
6ZS2.25×105	50	144	4	10ZS2.25×105	50	144	4
6ZS2.25×105	50	144	8	10ZS2.25×105	50	144	8
6ZS2.25×105	50	144	12	10ZS2.25×105	50	144	11.711
6ZS2.25×105	50	144	16	10ZS2.25×105	50	144	12
6ZS2.25×105	50	144	20	10ZS2.25×105	50	144	16
6ZS2.25×105	50	144	23.481	10ZS2.25×105	50	144	20
6ZS2.25×105	50	144	90	10ZS2.25×105	50	144	90
6ZS2.25×105	50	180	-8	10ZS2.25×105	50	180	-8
6ZS2.25×105	50	180	-4	10ZS2.25×105	50	180	-4
6ZS2.25×105	50	180	0	10ZS2.25×105	50	180	0
6ZS2.25×105	50	180	4	10ZS2.25×105	50	180	4
6ZS2.25×105	50	180	8	10ZS2.25×105	50	180	8
6ZS2.25×105	50	180	12	10ZS2.25×105	50	180	11.711

6ZS2.25×105	50	180	16	10ZS2.25×105	50	180	12
6ZS2.25×105	50	180	20	10ZS2.25×105	50	180	16
6ZS2.25×105	50	180	23.481	10ZS2.25×105	50	180	20
6ZS2.25×105	50	180	90	10ZS2.25×105	50	180	90
6ZS2.25×105	50	240	-8	10ZS2.25×105	50	240	-8
6ZS2.25×105	50	240	-4	10ZS2.25×105	50	240	-4
6ZS2.25×105	50	240	0	10ZS2.25×105	50	240	0
6ZS2.25×105	50	240	4	10ZS2.25×105	50	240	4
6ZS2.25×105	50	240	8	10ZS2.25×105	50	240	8
6ZS2.25×105	50	240	12	10ZS2.25×105	50	240	11.711
6ZS2.25×105	50	240	16	10ZS2.25×105	50	240	12
6ZS2.25×105	50	240	20	10ZS2.25×105	50	240	16
6ZS2.25×105	50	240	23.481	10ZS2.25×105	50	240	20
6ZS2.25×105	50	240	90	10ZS2.25×105	50	240	90

Note: θ is angle between axis of bending and major principal axis, see Fig. 1.

5.4 Full Moment-Deformation Results

Moment-deformation results for all cases are provided in Fig. 10-19. In each case the moment vs. mid-length lateral deformation, mid-length vertical deformation, and mid-length cross-section in-plane twist are shown for the full range of different bending axes (i.e., different θ) . Classical lateral-torsional buckling bifurcation behavior is observed in the case where the loading is about the major principal-axis ($\theta=0$), otherwise the inclined bending axis has an overall effect quite similar to a twist imperfection.

Generally, all the simulations converge at large enough deformations to achieve a peak moment. In some cases, e.g. Fig.19 for the 10ZS2.25×105 section, more than one peak moment is observed. Members with longer unbraced lengths typically have greater potential for multiple peak moments. After bifurcation and buckling these specific members continue to rotate significantly and eventually engage minor principal-axis yielding and cross-section plastification.

In terms of failure type, all the simulations deform in bending and rotation. For shorter members, the region near the web-flange connection in the web will typically yield first under tension. Subsequently the yield region extends to the flange part and eventually reaches to the lip. Once the yielded region forms a mechanism, the deformation will concentrate at this location, and the other regions will experience elastic recovery. The region near the member ends generally deforms gradually with the applied moment. For longer members, larger displacement and web rotation are observed.

When the axes of bending is rotated in a positive angle direction from the principal axes the peak moment is larger than those in the negative angle direction. Using 6ZS2.25×105 section under 50ksi yield moment with 144in length as an example when the axis of bending is -8 degree inclined from major principal axis, the first yield will happen on the lip and lip-flange junction. In the end, most of the damage occurs at one side of the flange, while the other side is stable. When the axis of bending is +8 degree inclined from major principal axis, the first yield will happen at the flange-web junction. In the end, most of the damage occurs at the web along the middle line and the buckling is prevalent through the whole section at the middle. See Fig. 20 for further illustration of this phenomenon.

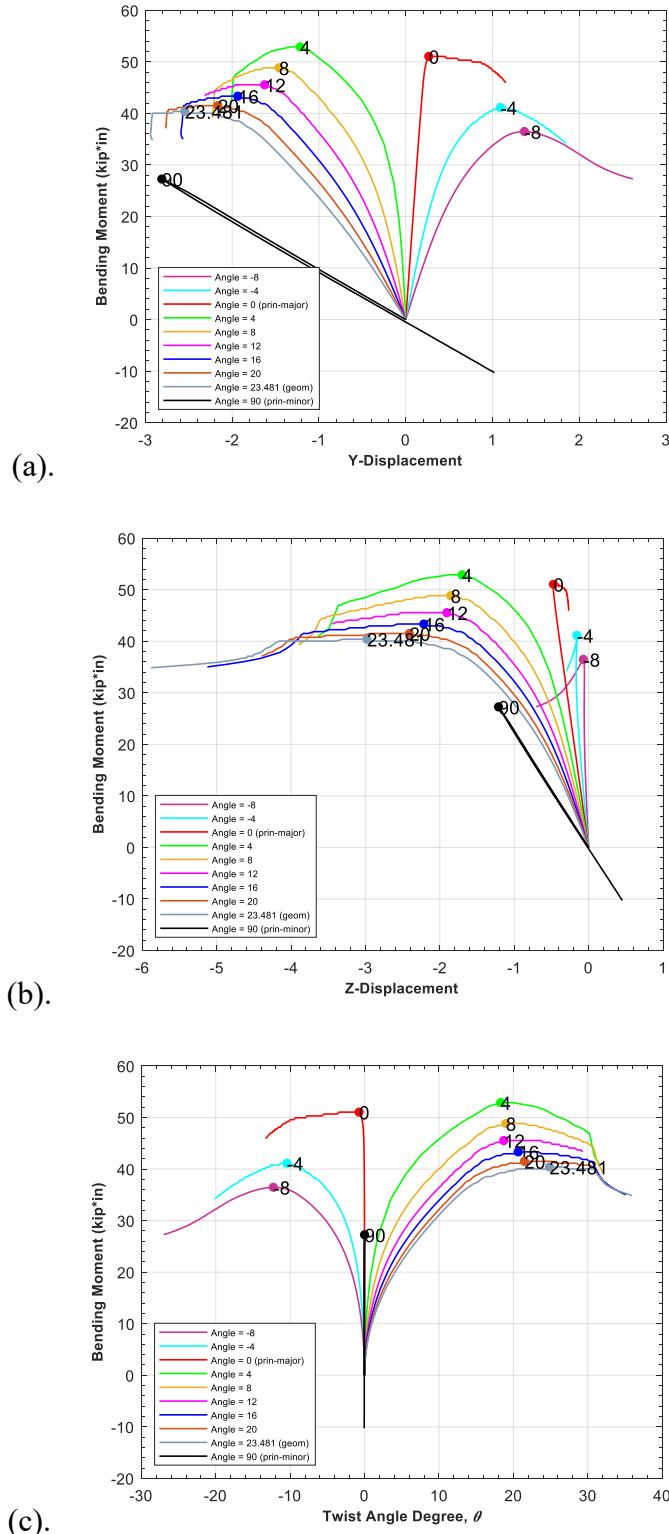


Figure 10. Moment-deformation plots for 6ZS2.25×105 with $F_y = 33$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

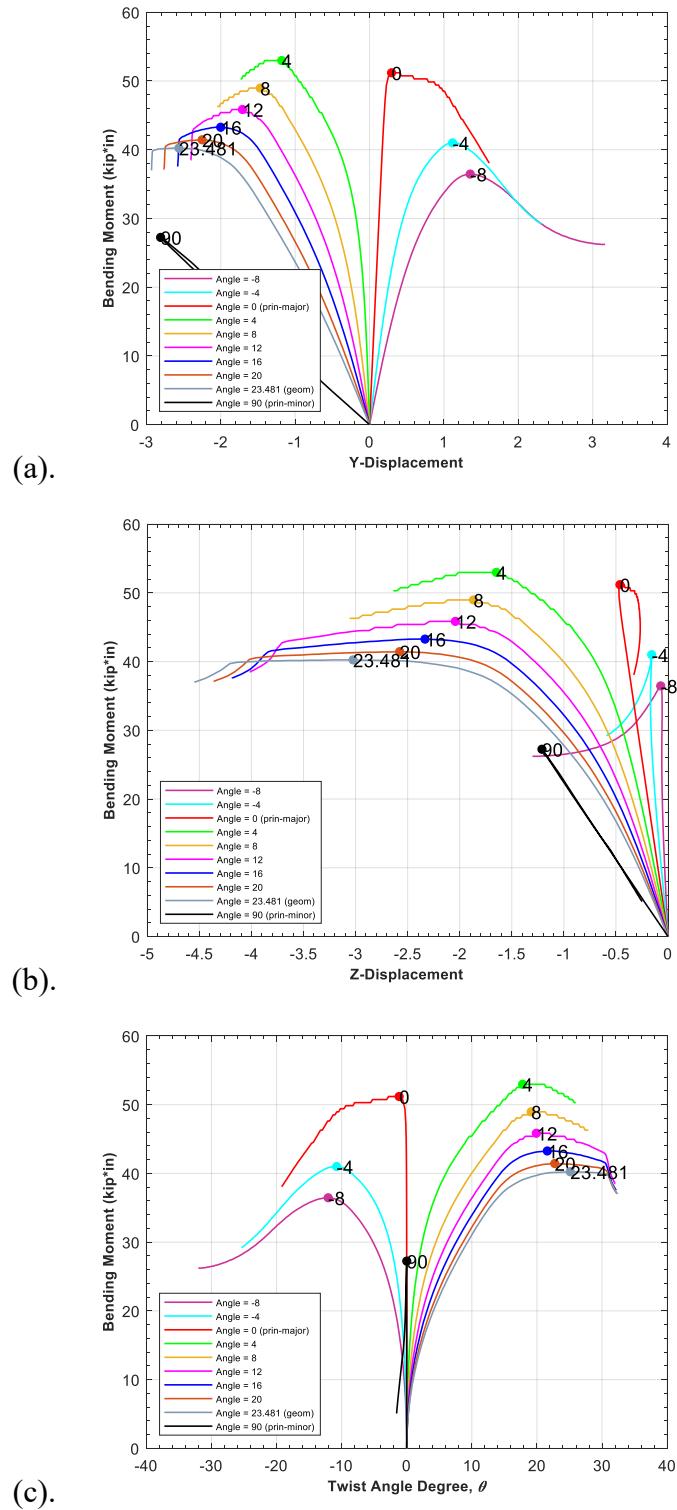


Figure 11. Moment-deformation plots for 6ZS2.25×105 with $F_y = 40$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

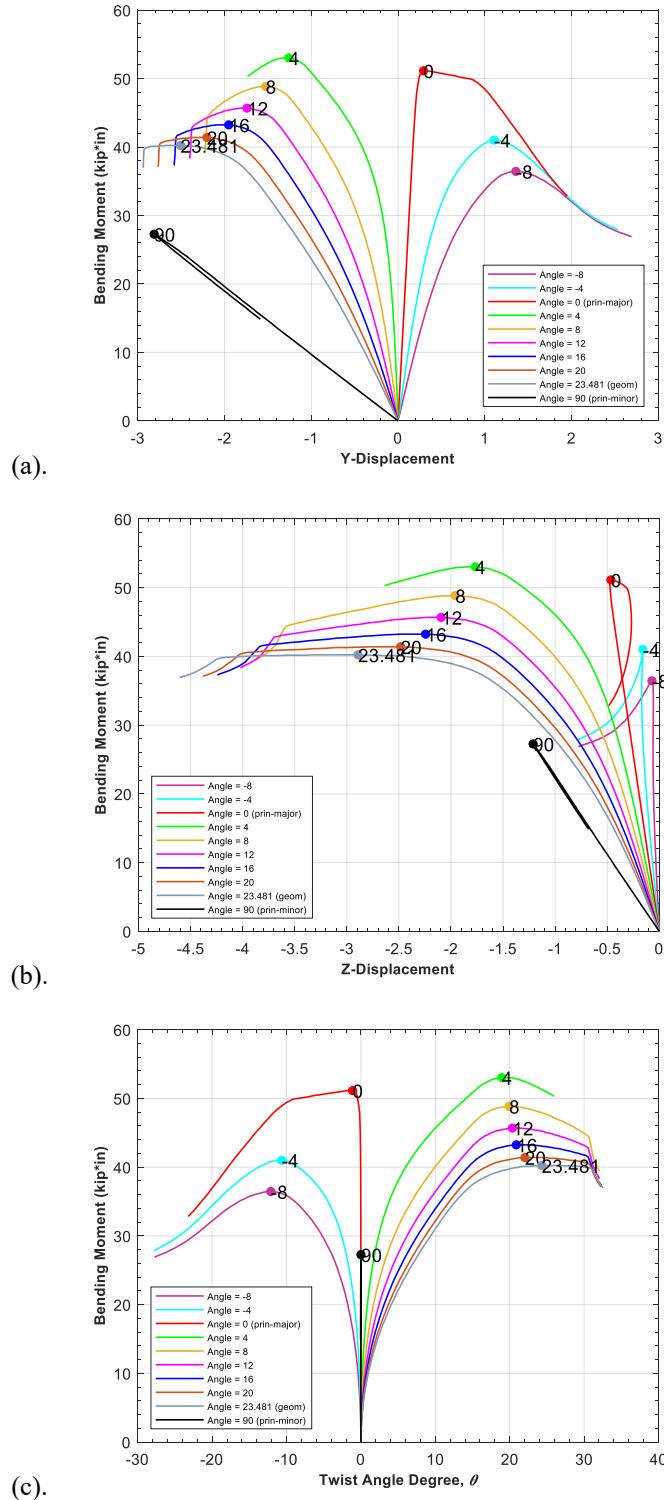


Figure 12. Moment-deformation plots for 6ZS2.25×105 with $F_y = 50$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

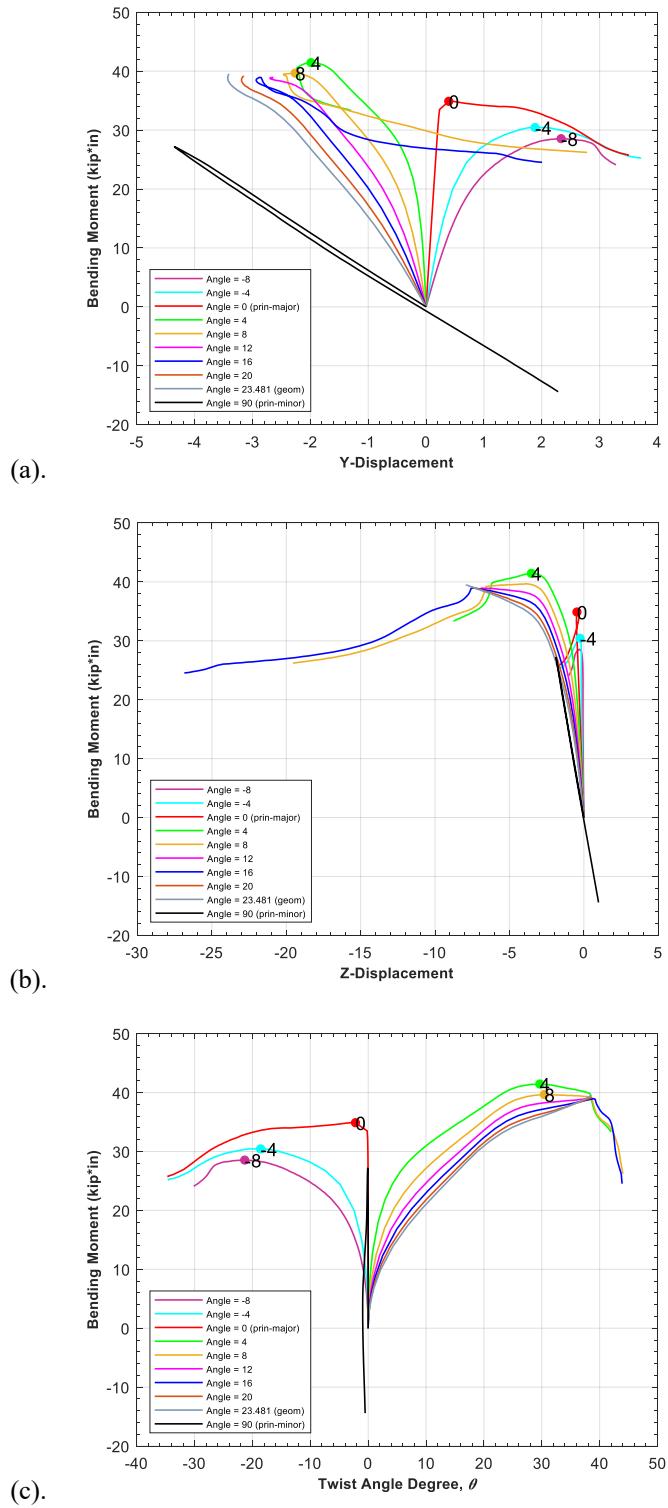


Figure 13. Moment-deformation plots for 6ZS2.25×105 with $F_y = 50$ ksi and $L = 180$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

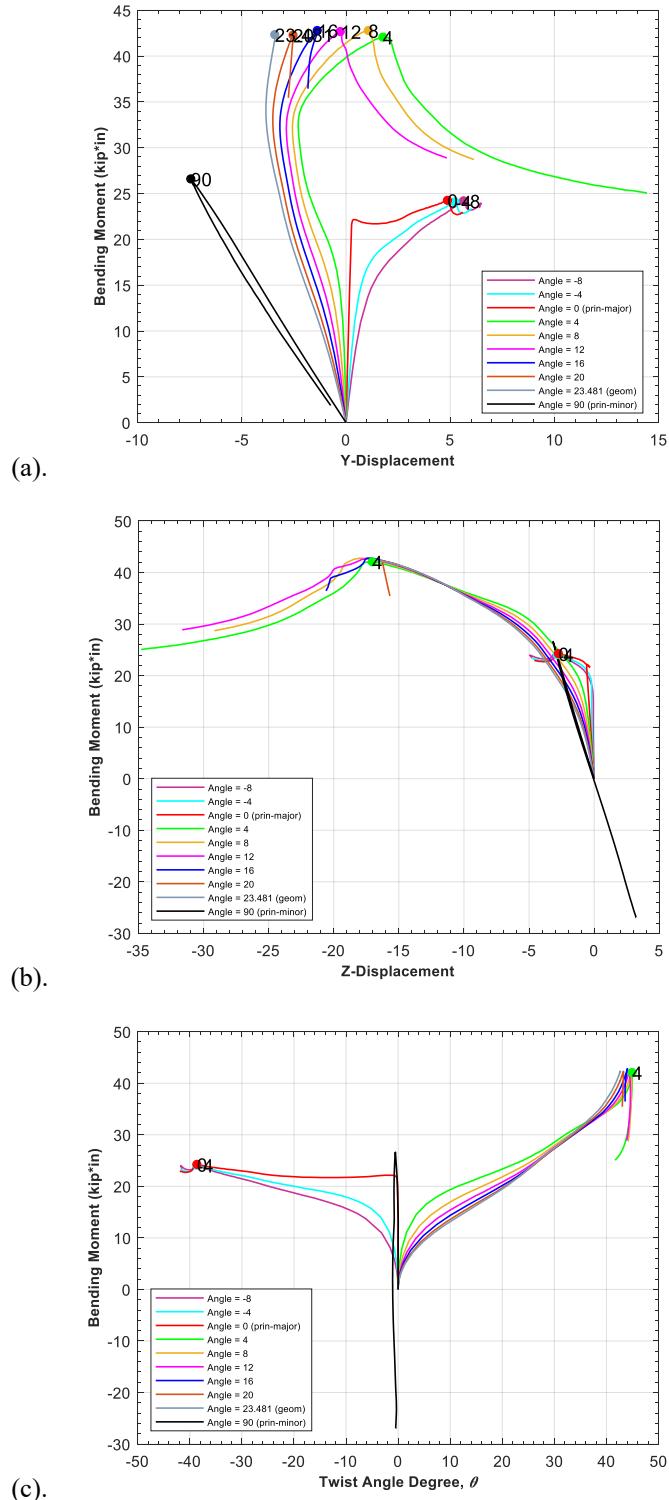


Figure 14. Moment-deformation plots for 6ZS2.25×105 with $F_y = 50$ ksi and $L = 240$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

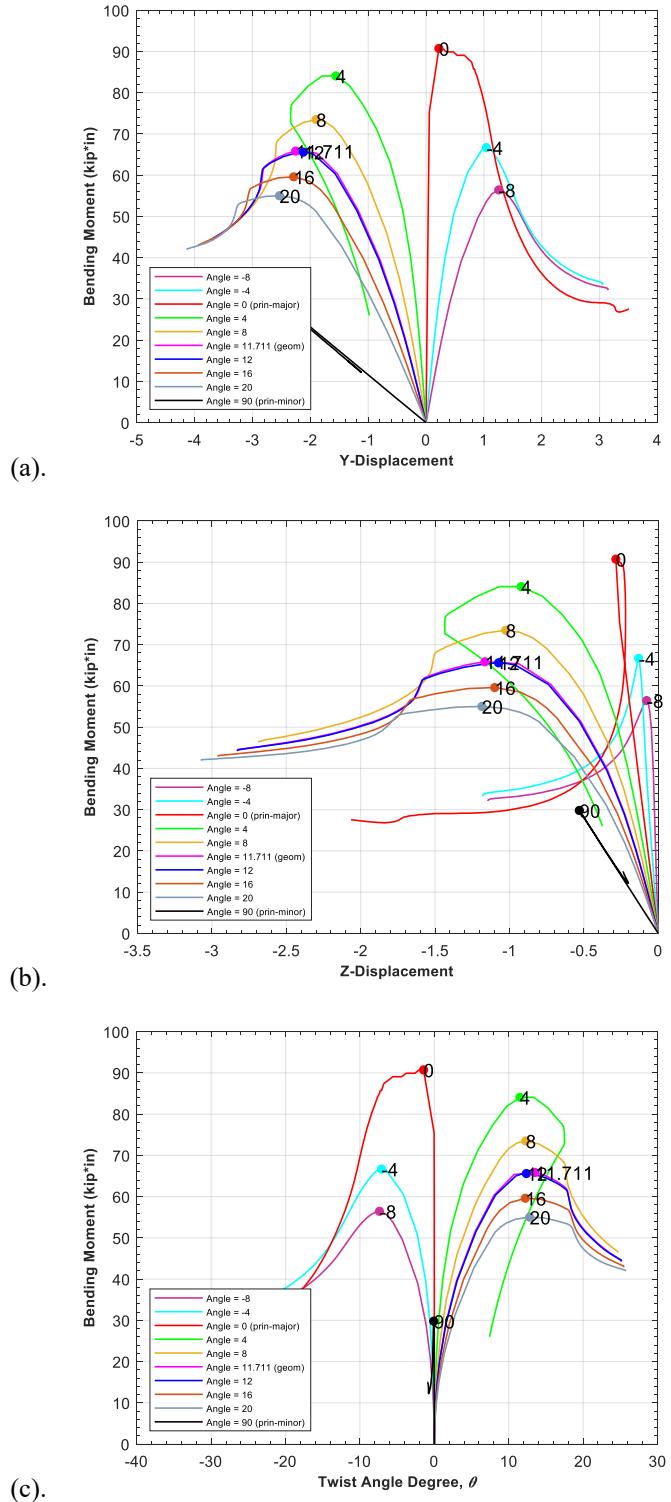


Figure 15. Moment-deformation plots for 10ZS2.25×105 with $F_y = 33$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

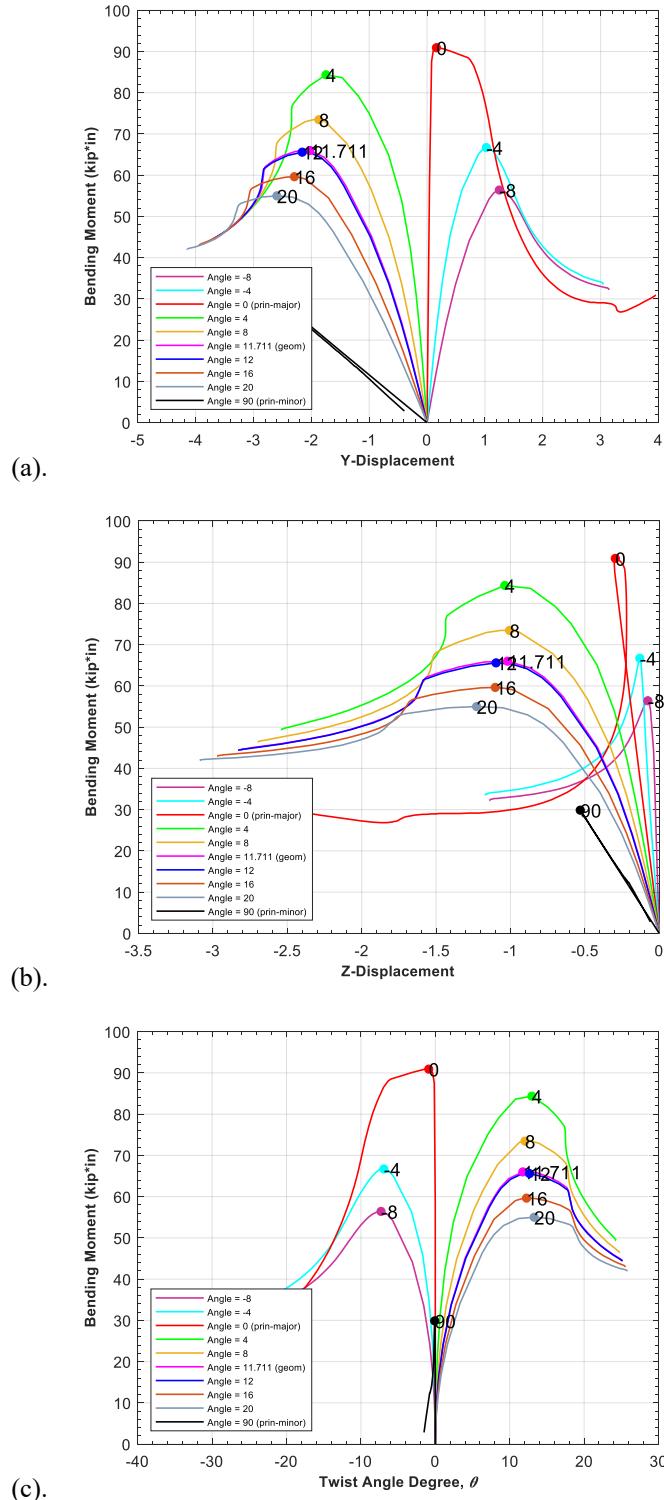


Figure 16. Moment-deformation plots for 10ZS2.25×105 with $F_y = 40$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

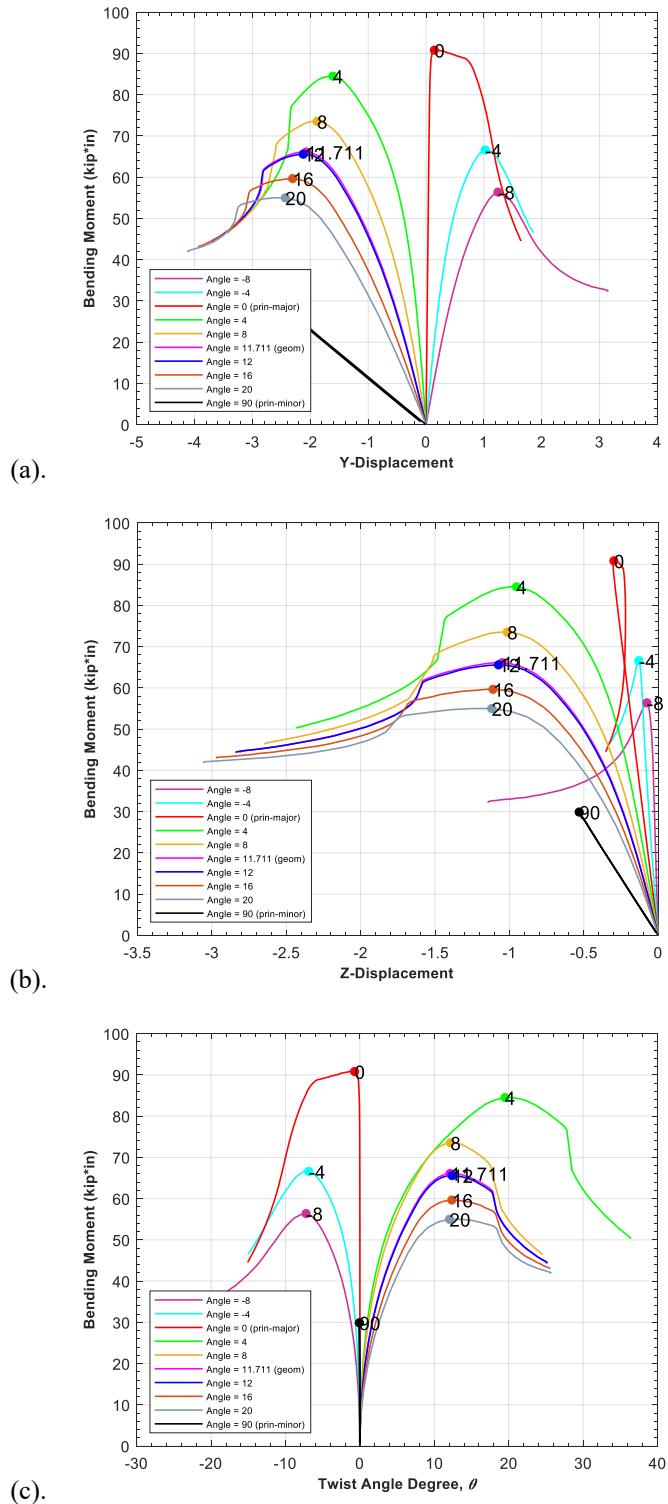


Figure 17. Moment-deformation plots for 10ZS2.25×105 with $F_y = 50$ ksi and $L = 144$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

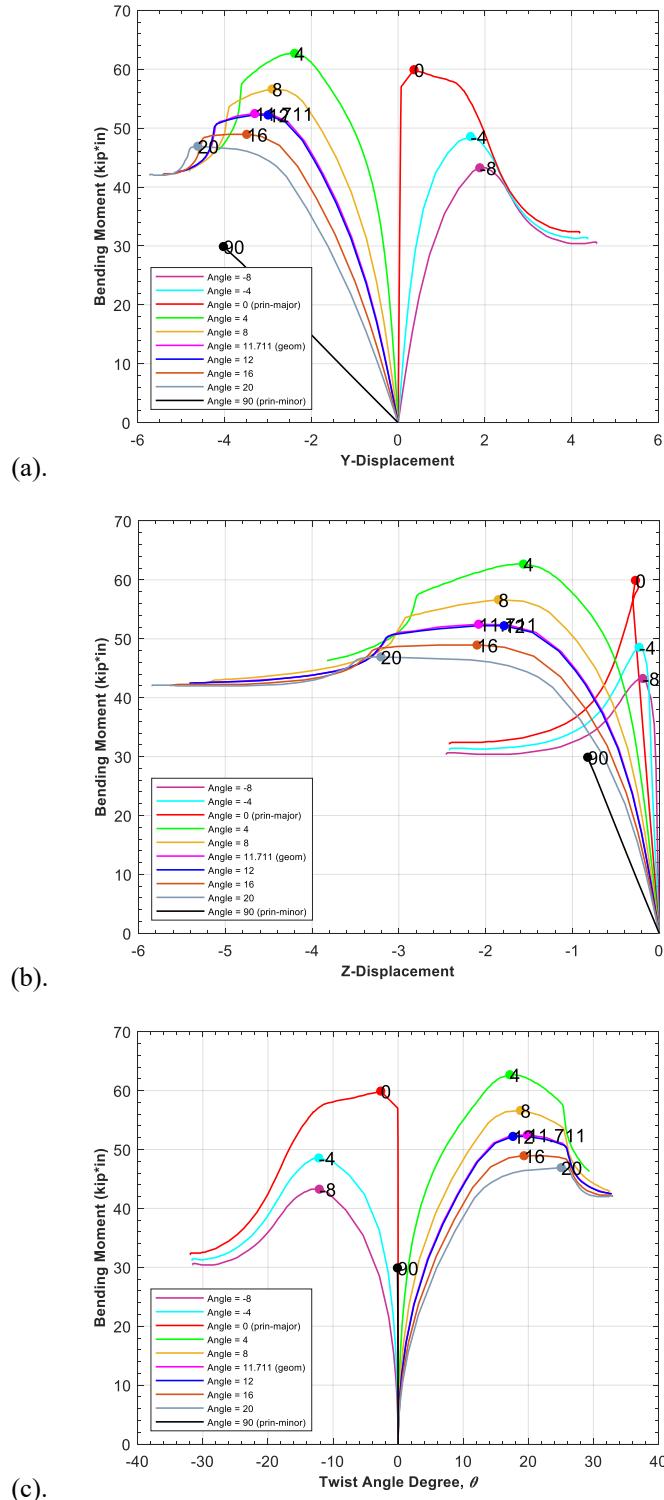


Figure 18. Moment-deformation plots for 10ZS2.25×105 with $F_y = 50$ ksi and $L = 180$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

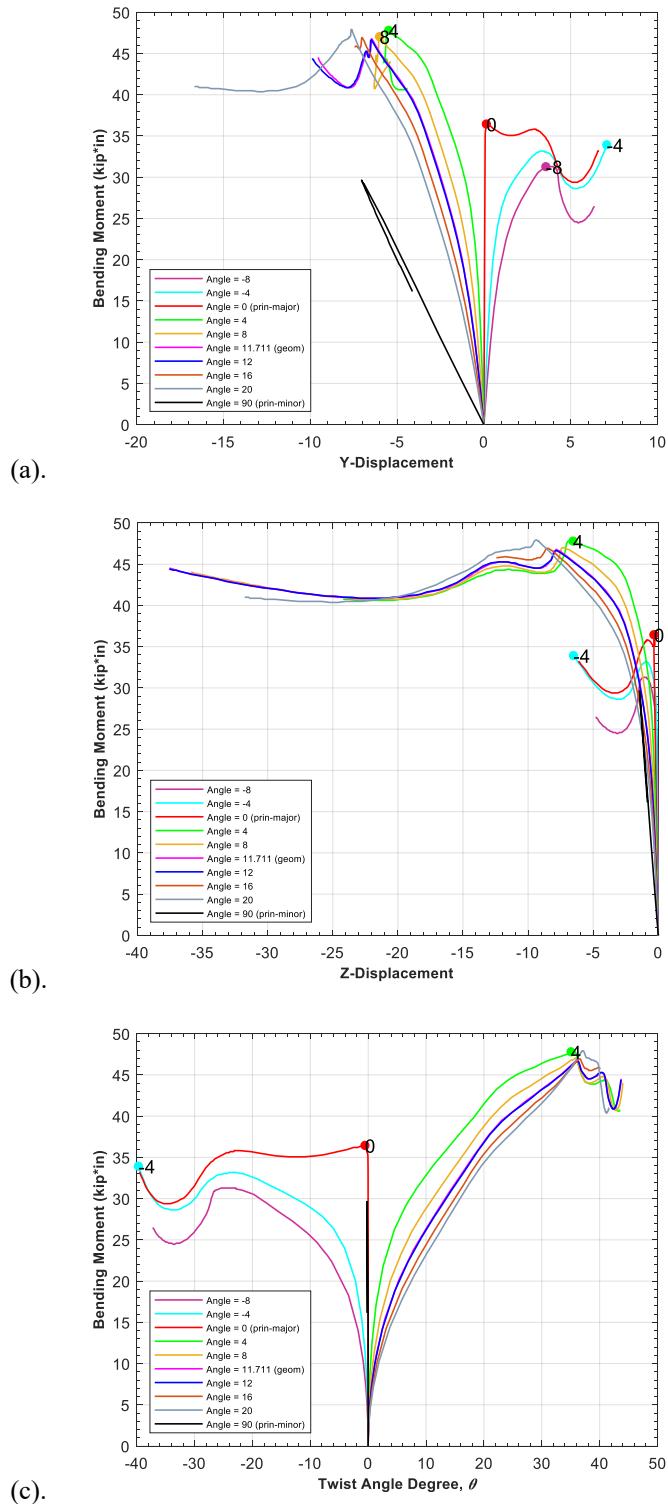


Figure 19. Moment-deformation plots for 10ZS2.25×105 with $F_y = 50$ ksi and $L = 240$ in. (a) lateral web deflection (x of Fig. 1, Y in ABAQUS model), (b) vertical web deflection (y in Fig. 1, Z in ABAQUS model), (c) web twist.

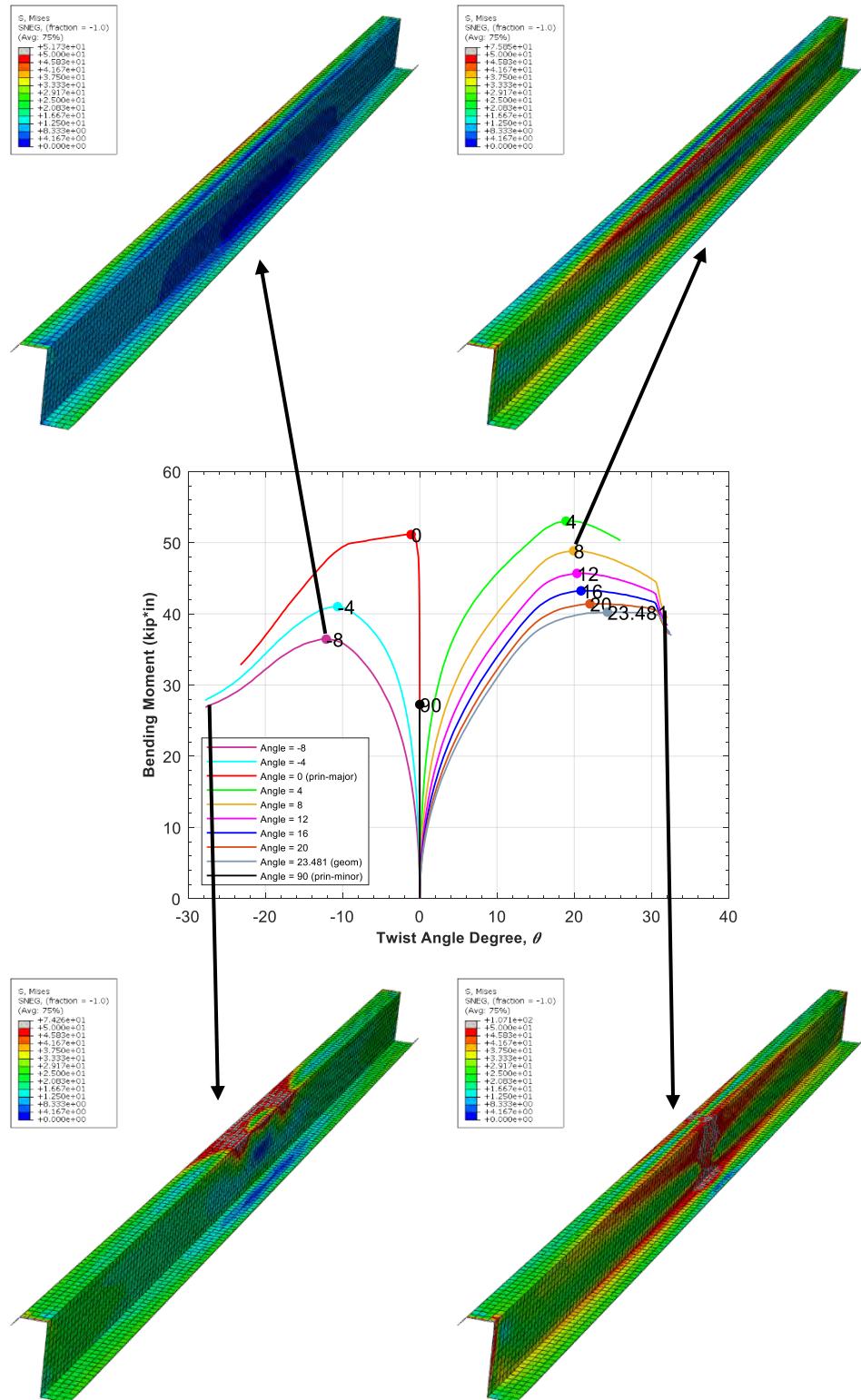


Figure 20. Lateral-torsional buckling in opposite directions for 6ZS2.25×105 with $F_y = 50$ ksi and $L = 144$ in.

5.5 Imperfection sensitivity

Cold-formed steel members have geometric imperfections due to the production process, shipping, and installation. Results are imperfection sensitive when the models have bifurcation; however, the imperfection sensitivity is reduced if primary deformation already exists in the buckling direction, e.g. in these models when twist has already initiated. This section of the report briefly explores how imperfections impact the LTB flexural capacity for the target sections under bending moment about the major principal axis (a case that should be imperfection sensitive).

A twist imperfection is applied. Only bending about the major principal axis ($\theta = 0$) is considered. An L/2292 imperfection is applied to the 6ZS2.25×105 and 10ZS2.25×105. The imperfection factor was estimated based on a maximum imperfection twist angle of no more than 2 degrees. L is the unbraced length in the member longitudinal direction (x-axis in the ABAQUS model). Yield strength is 50 ksi for all cases in this section.

As shown in the figures introduction of the 2 deg. twist imperfection eliminates the sharp bifurcation nature of the response for the case with bending about the major principal axis (angle = 0 deg.), and provides response in essence equivalent to bending about an axis approximately 2 deg. from the principal axis.

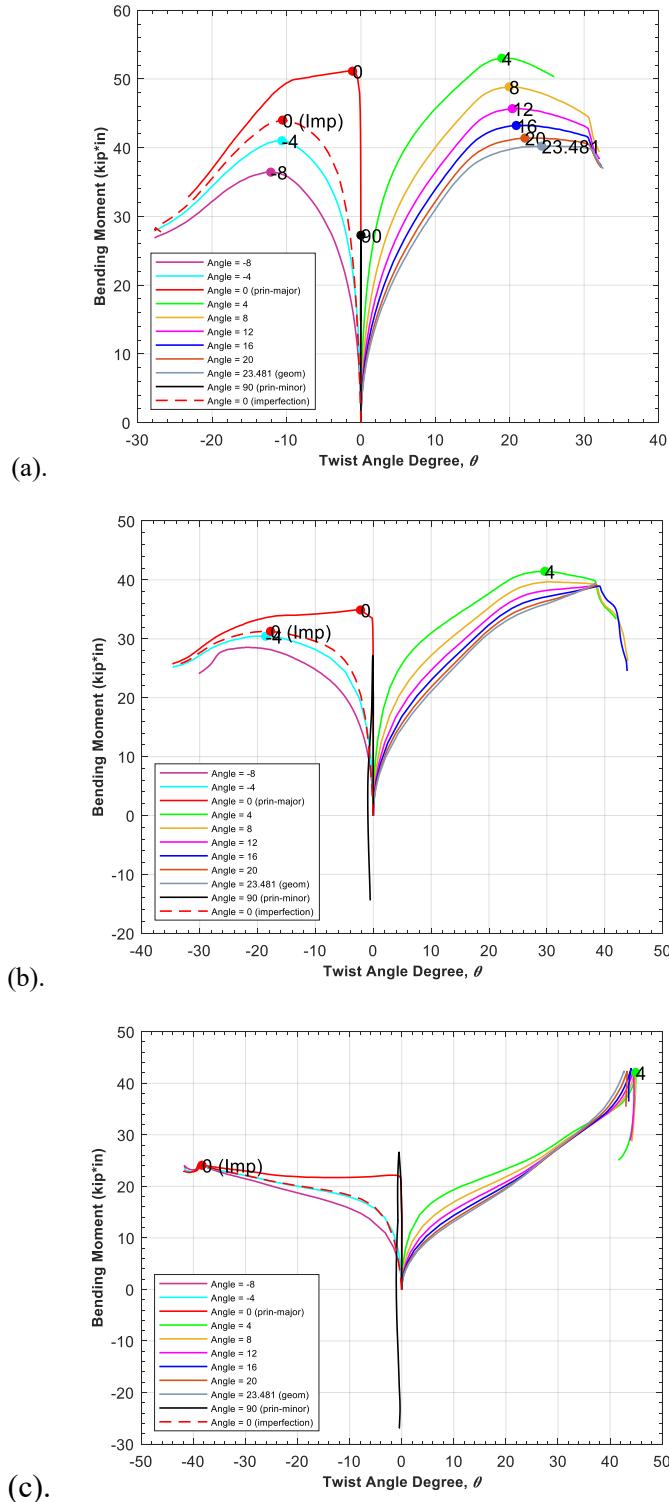


Figure 21. Moment-web twist plots for 6ZS2.25×105 section with $F_y = 50$ ksi. (a) $L = 144$ in, (b) $L = 180$ in, (c) $L = 240$ in.

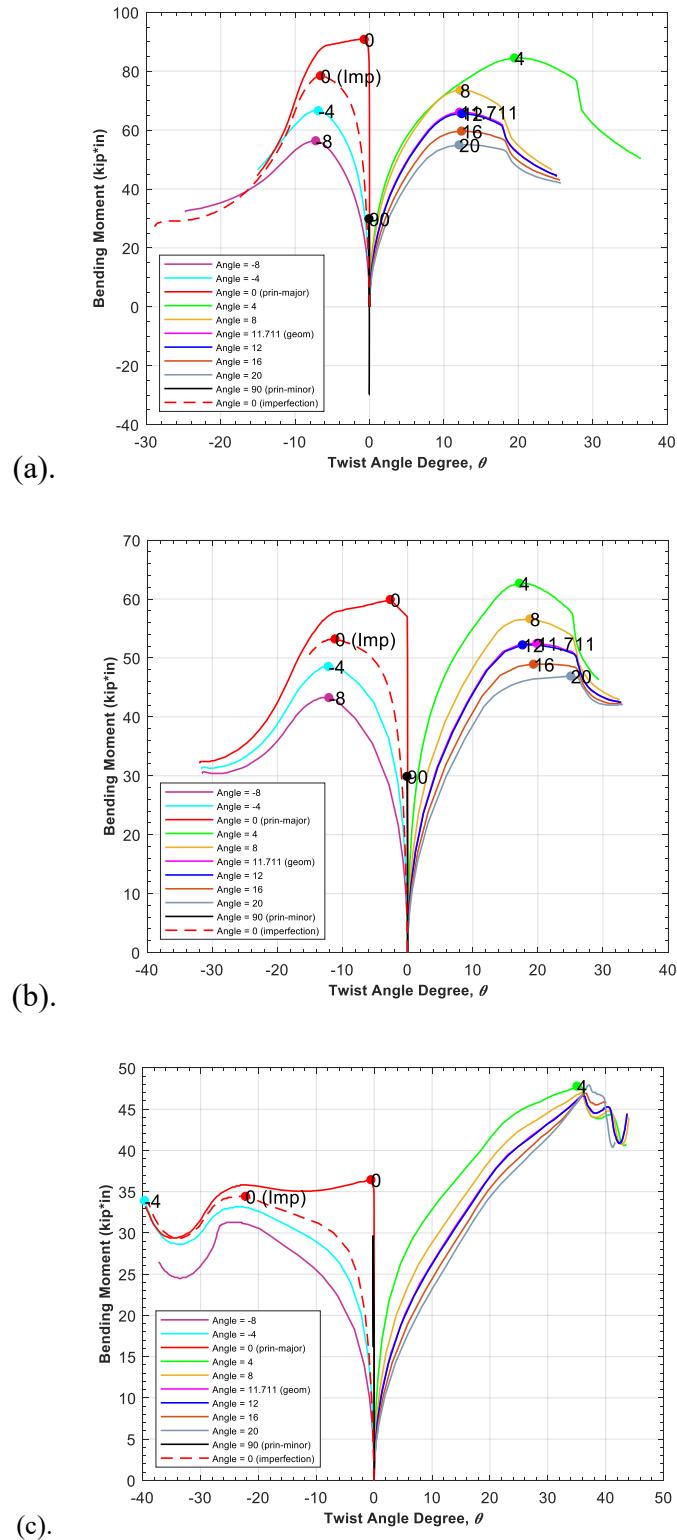


Figure 22. Moment-web twist plots for 10ZS2.25×105 section with $F_y = 50$ ksi. (a) $L = 144$ in, (b) $L = 180$ in, (c) $L = 240$ in.

6 Studied Design Methods

Nominal flexural capacity was predicted by three design methods: (1) AISI S100-16 approximate approach, (2) AISI S100-16 linear interaction approach, and (3) a new method considering direct bi-axial bending consistent with recent Direct Strength Method proposals. The simulation results are compared with the proposed provisions for both stability and strength determination.

6.1 Method 1: AISI S100-16 Approximate Approach

Method 1 requires critical elastic lateral-torsional buckling stress F_{cre} to be calculated using Eq. F2.1.3-1 from AISI S100-16, which is an approximate expression for point-symmetric sections bending about the geometric axis:

$$F_{cre} = \frac{C_b r_o A}{2S_f} \sqrt{\sigma_{ey}\sigma_t} \quad (2)$$

where C_b is permitted to be conservatively taken as unity for all cases, r_o is the polar radius of gyration of cross-section about shear center, A is the cross-section area, S_f is the elastic section modulus, σ_{ey} and σ_t are the critical axial stress for elastic buckling about x axis and torsion. The nominal stress F_n is then determined as :

$$\begin{aligned} & \text{When } F_{cre} \geq 2.78F_y, \text{ yield limitation} \\ & F_{ne} = F_y \end{aligned} \quad (3)$$

When $2.78F_y > F_{cre} > 0.56F_y$, inelastic buckling

$$F_n = \frac{10}{9}F_y \left(1 - \frac{10F_y}{36F_{cre}}\right) \quad (4)$$

When For $F_{cre} \leq 0.56F_y$, elastic buckling

$$F_n = F_{cre} \quad (5)$$

The nominal flexural strength, M_{ne} , is defined by:

$$M_{ne} = S_f F_n \quad (6)$$

Common practice is to consider only bending about the geometric axis. So, if the perpendicular component of the moment is ignored, the strength for the axis of the applied moment is given by Eq. 7 where β is the angle between the axis of bending and the geometric axis.

$$M_n = \frac{M_{ne}}{\cos(\beta)} \quad (7)$$

6.2 Method 2: AISI S100-16 Interaction Approach

Method 2 requires the strength be calculated independently about the major and minor principal axis, designated as M_{n1} and M_{n2} and then combined in an interaction formula based on the demand.

The elastic lateral-torsional buckling moment, M_{cre} , or stress F_{cre} can be calculated using Glauz (2017) or CFS or CUFSM. Here we illustrate for CUFSM that first one finds the elastic lateral-torsional buckling moments for bending about each principal axis:

$$M_{cre1} = M_{ref} \times LF(cu fsm)_{0^\circ} \quad (8)$$

$$M_{cre2} = M_{ref} \times LF(cu fsm)_{90^\circ} \quad (9)$$

The yield moment about each principal axis can be defined as:

$$M_{y1} = F_y \times \frac{M_{ref}}{F_{max1}} \quad (10)$$

$$M_{y2} = F_y \times \frac{M_{ref}}{F_{max2}} \quad (11)$$

Since the neutral axis does not align with axis of resultant moment for point-symmetric section, the member plastic moment M_p can be defined by using plastic natural axis (PNA) which is the interface line between F_y tension and F_y compression areas. The PNA passes through the centroid of the section. The plane of bending passes through the centroids of the tension and compression areas, and the axis of bending is perpendicular to the plane of bending. The plastic moment about axis of bending may be expressed as:

$$M_{pi} = \frac{D \cdot A \cdot F_y}{2} \quad (12)$$

where i is 1 or 2 depending on the axis, D is the distance between centroids of tension and compression areas, A is the cross-section area, and F_y is the yield stress. These calculations assume the stress is applied to line elements at the centerline of the thickness. The PNA location is divided into 4 cases depending on which elements the PNA crosses. Appendix 10.1 shows the full results for plastic moment.

M_{nei} can be calculated with the similar process as method 1, if we ignore the inelastic reserve then:

$$\text{When } M_{crei} \geq 2.78M_{yi}, \text{ yield limitation} \\ M_{nei} = M_{yi} \quad (13)$$

When $2.78M_{yi} > M_{crei} > 0.56M_{yi}$, inelastic buckling

$$M_{nei} = \frac{10}{9}M_{yi} \left(1 - \frac{10M_{yi}}{36M_{crei}}\right) \quad (14)$$

When $M_{crei} \leq 0.56M_{yi}$, elastic buckling
 $M_{nei} = M_{crei}$ (15)

If inelastic reserve is included then the following additional branches of the LTB strength curve are engaged:

When $M_{crei} > 18.9M_{yi}$, inelastic reserve
 $M_{nei} = M_{pi}$ (16)

When $M_{crei} > 2.78M_{yi}$, inelastic buckling
 $M_{nei} = M_{pi} - (M_{pi} - M_{yi}) \frac{\sqrt{M_{yi}/M_{crei}} - 0.23}{0.37} \leq M_{pi}$ (17)

A limitation imposed by S100-16 for local inelastic reserve

$$\frac{\sqrt{M_{yi}/M_{crei}} - 0.23}{0.37} \geq \frac{1}{9} \quad (18)$$

The source of Eq. (18) can be understood by recognizing that with global inelastic reserve ($M_{nei} > M_{yi}$), we should calculate the inelastic reserve for local buckling according to AISI S100-16 Eq. F3.2.3. as we want to use the minimum value between local and global buckling moment.

$$M_{n\ell} = M_y + (1 - \frac{1}{C_{y\ell}^2})(M_p - M_y) \quad (19)$$

and the maximum value of $C_{y\ell}$ (ratio of ultimate strain to yield strain) is 3. Finally M_{n1} and M_{n2} are determined by the minimum result between M_{nei} and $M_{n\ell i}$.

$$M_{n1} = \min(M_{ne1}, M_{n\ell 1}) \quad (20)$$

$$M_{n2} = \min(M_{ne2}, M_{n\ell 2}) \quad (21)$$

These strength expressions are used in the linear interaction equation of S100:

$$\frac{M_1}{M_{n1}} + \frac{M_2}{M_{n2}} \leq 1.0 \quad (22)$$

For the special case of bending by moment M about an arbitrary axis at angle θ demand M_1 and M_2 can be written simply in terms of M :

$$\frac{M|\cos \theta|}{M_{n1}} + \frac{M|\sin \theta|}{M_{n2}} \leq 1.0 \quad (23)$$

Which when solved for M provides the moment strength about an arbitrary axis:

$$M_n = \frac{1}{\frac{|\cos \theta|}{M_{n1}} + \frac{|\sin \theta|}{M_{n2}}} \quad (24)$$

6.3 Method 3: Direct Bi-axial Bending Approach

Method 3 considers the axis of bending directly. The strength formulas are familiar:

When $\lambda_e \leq 0.23$, inelastic reserve.
 $M_n = M_p$ (25)

When $0.23 < \lambda_e < 0.60$, inelastic buckling with reserved capacity.

$$M_n = M_p - (M_p - M_y) \frac{\sqrt{M_y/M_{cre}} - 0.23}{0.37} \leq M_p (26)$$

When $0.60 < \lambda_e < 1.34$, inelastic buckling

$$M_n = \frac{10}{9} \left(1 - \frac{10}{36} \lambda_e^2\right) M_y (27)$$

When $1.34 < \lambda_e$, elastic buckling (28)

$$M_n = M_{cre}$$

Except here, M_y , M_p , and M_{cre} are for bending about the arbitrary axis. M_y is readily defined by first yield at an extreme fiber, M_p is more complex for bending about an arbitrary axis and calculations are detailed in the Appendix, M_{cre} may be determined using CUFSM or CFS elastic LTB analysis, or as an alternative method, M_{cre} also can be determined using the analytical method developed in Glauz (2017):

$$M_{cre} = C_b r_o \sqrt{P_e P_t} (29)$$

$$P_e = \frac{\pi^2 E (I_x I_y - I_{xy}^2)}{I_b (K_f L_f)^2} = \frac{\pi^2 E I_1 I_2}{I_b (K_f L_f)^2} (30)$$

$$P_t = \frac{1}{r_o^2} \left[GJ + \frac{\pi^2 E C_w}{(K_t L_t)^2} \right] (31)$$

Note, for those cases with global inelastic reserve ($M_{ne} > M_y$), we should calculate the inelastic reserve for local buckling according to AISI S100-16 Eq. F3.2.3. as we want to use the minimum value between local and global buckling moment.

$$M_{n\ell} = M_y + \left(1 - \frac{1}{C_{y\ell}^2}\right) (M_p - M_y) (32)$$

Noting that the maximum value of $C_{y\ell}=3$, then

$$M_{n\ell-\max} = M_y + \left(1 - \frac{1}{9}\right) (M_p - M_y) (33)$$

which effectively limits the strength to slightly below M_p .

6.4 Sample Calculation for 6ZS2.25×105 Cross-section

Determine the nominal flexural strength for bending about an inclined axis (i.e. $\theta = -8^\circ$)

6.4.1 Method 1

First, determine the nominal flexural strength for bending about geometric axis.

$$\sigma_{ey} = \frac{\pi^2 E}{\left(\frac{K_y L_y}{r_y}\right)^2} = 21.589 \text{ (ksi)}$$

$$\sigma_t = \frac{1}{Ar_0^2} \left[GJ + \frac{\pi^2 EC_w}{(K_t L_t)^2} \right] = 289.679 \text{ (ksi)}$$

$$F_{cre} = \frac{C_b r_o A}{2 S_f} \sqrt{\sigma_{ey} \sigma_t} = 16.67 \text{ (ksi)}$$

$$\frac{F_{cre}}{F_y} = \frac{16.67}{50} = 0.334 < 0.56$$

$$F_n = F_{cre} = 16.67 \text{ (ksi)}$$

$$M_{ne} = S_f F_n = 2.371 \times 16.67 = 39.527 \text{ (k * in)}$$

Now, determine the nominal flexural strength for the inclined axis (e.g. $\theta = -8^\circ$)

$$M_n = \frac{M_{ne}}{\cos(\beta)} = \frac{39.527}{\cos(-8^\circ - 23.481^\circ)} = \mathbf{46.349} \text{ (k * in)}$$

The completed solution of method 1 is shown in Table 7.

Table 7. Method 1: AISI S100-16 Approximate Approach (6ZS2.25×105, Fy=50ksi, L=144in)

θ	I_x	H	S_f	F_{cre}	F_n	$M_{n,1}$
degree	in^4	in	in^3	ksi	ksi	kip-in
23.481	7.113	6	2.371	16.67	16.67	39.527
-8						46.349
-4						44.554
0						43.095
4						41.927
8						41.015
12						40.334
16						39.866
20						39.600
23.481						39.527
90						99.203

6.4.2 Method 2

First, determine the nominal flexural strength for bending about principal axis.

$$M_{cre1} = M_{ref} \times LF(cu fsm)_0 = 49.567(k * in)$$

$$M_{cre2} = M_{ref} \times LF(cu fsm)_{90} = 145.371(k * in)$$

$$M_{y1} = F_y \times \frac{M_{ref}}{F_{max1}} = 116.393(k * in), M_{y2} = F_y \times \frac{M_{ref}}{F_{max2}} = 23.173(k * in)$$

$$M_{p1} = \frac{D_1 AF_y}{2} = 126.675(k * in), M_{p2} = \frac{D_2 AF_y}{2} = 42.050(k * in)$$

(Completed M_p refer to Appendix 10.1)

$$\frac{M_{cre1}}{M_{y1}} < 0.56, M_{n1} = M_{cre1} = 49.567$$

$$18.9 > \frac{M_{cre2}}{M_{y2}} > 2.7, M_{ne2} = M_p - (M_p - M_y) \frac{\sqrt{\frac{M_y}{M_{cre}}} - 0.23}{0.37} = 33.415(k * in)$$

$$M_{h\ell 2} = M_y + \left(1 - \frac{1}{C_{y\ell}^2}\right)(M_p - M_y) = 32.222(k * in)$$

$$M_{n2} = \min(M_{ne2}, M_{nl2}) = 32.222(k * in)$$

Now, determine the nominal flexural strength for the inclined axis (e.g. $\theta = -8^\circ$)

$$M_n = \frac{1}{\frac{|\cos \theta|}{M_{n1}} + \frac{|\sin \theta|}{M_{n2}}} = \frac{1}{\frac{|\cos(-8^\circ)|}{49.567} + \frac{|\sin(-8^\circ)|}{32.222}} = 41.156(k * in)$$

The completed solution of method 2 is shown in Table 8.

Table 8. Method 2: AISI S100-16 Interaction Approach (6ZS2.25×105, $F_y=50\text{ksi}$, $L=144\text{in}$)

θ	M_{ref}	LF (cu fsm)	M_{cre}	F_{max} (cu fsm)	M_y/F_y (M_{ref}/F_{max})	M_y	M_p	$M_{n,2}$	
degree	kip-in		kip-in	ksi		kip-in	kip-in	kip-in	
0	55.646	0.891	49.567	23.905	2.328	116.393	126.675	49.567	(M_{n1})
90	55.646	2.612	145.371	120.067	0.463	23.173	42.050	32.222	(M_{n2})
-8								41.156	
-4								44.862	
0								49.567	
4								44.862	
8								41.156	
12								38.188	
16								35.781	
20								33.815	
23.481								32.394	
90								32.222	

6.4.3 Method 3

Determine nominal flexural strength for a sample inclined axis (e.g. $\theta = -8^\circ$)

$$M_{cre} = M_{ref} \times LF(cu fsm) = 49.975(k * in)$$

$$M_y = F_y \times \frac{M_{ref}}{F_{max}} = 74.150(k * in)$$

$$\lambda_e = \sqrt{\frac{M_y}{M_{cre}}} = 1.218$$

$$0.60 < \lambda_e < 1.34$$

$$M_n = \frac{10}{9} M_y \left(1 - \frac{10M_y}{36M_{cre}}\right) = 48.432(k * in)$$

The completed solution of method 3 is shown in Table 9.

Table 9. Method 3: Direct Bi-axial Bending Approach (6ZS2.25×105, Fy=50ksi, L=144in)

θ	M _{ref}	M ₁	M ₂	F _{max} (cu fsm)	M _y /F _y (M _{ref} /F _{max})	LF (cu fsm)	M _y	M _{cre}	M _p	λ_e	M _{n,3}
degree	kip-in	kip-in	kip-in	ksi			kip-in	kip-in	kip-in		kip-in
-8	55.646	55.105	7.744	37.523	1.483	0.898	74.150	49.975	97.173	1.218	48.432
-4	55.646	55.511	3.882	29.342	1.896	0.893	94.825	49.664	109.825	1.382	49.664
0	55.646	55.646	0.000	23.905	2.328	0.891	116.393	49.567	126.675	1.532	49.567
4	55.646	55.511	-3.882	23.908	2.328	0.893	116.377	49.684	146.500	1.530	49.684
8	55.646	55.105	-7.744	29.594	1.880	0.899	94.018	50.016	130.948	1.371	50.016
12	55.646	54.430	-11.570	35.135	1.584	0.909	79.190	50.571	117.196	1.251	49.716
16	55.646	53.491	-15.338	40.505	1.374	0.923	68.690	51.359	105.228	1.156	47.968
20	55.646	52.291	-19.032	45.678	1.218	0.942	60.911	52.396	94.947	1.078	45.824
23.481	55.646	51.038	-22.173	50.000	1.113	0.962	55.646	53.516	87.252	1.020	43.971
90	55.646	0.000	-55.646	120.067	0.463	2.612	23.173	145.371	42.050	0.399	32.222

Note:

θ is the axis of bending inclined from major principal axis.

M_{ref} is reference moment about axis of bending

When the axis of bending inclines to major and minor principal axis, the value of applied moment regards bending axis is equal to M_{ref}.

7 Evaluation of Design Methods

Simulation-to-predicted strength is provided in Table 10. The results are separated into three slenderness ($\lambda_e = \sqrt{M_y/M_{cre}}$) ranges: low, less than 0.6; medium from 0.6 to 1.5; and high, greater than 1.5 called slender. A simulation-to-predicted ratio equal to 1 means the design method for the member was exactly matched with the collapse analysis peak moment under the specific load condition.

Some of the simulation results for slender members had unusually high ultimate moments. For the 6ZS2.25×105 with unbraced length of 240 in. and an axis of bending having positive θ , the ultimate moments were approximately equal to the minor axis plastic moment, which was higher than the elastic buckling moment, and also higher than the ultimate moment for a shorter unbraced length. It was observed that these cases had significant rotation (this behavior is not unique to point-symmetric sections, similar behavior has been observed in tests and simulations on lipped Cees). This mode of failure and abnormally high moment strength was not the target of this study. Therefore Table 11 provides a summary for all three methods while excluding the 6ZS2.25×105 with unbraced length equal to 240 in..

Table 10. Simulation-to-predicted ratios summary for all three methods.

Section & θ	Average of $M_{max1}/M_{n,1}$			Average of $M_{max1}/M_{n,2}$			Average of $M_{max1}/M_{n,3}$			Average of $M_{max1}/M_{n,1}$	Average of $M_{max1}/M_{n,2}$	Average of $M_{max1}/M_{n,3}$
	Low	Medium	Slender	Low	Medium	Slender	Low	Medium	Slender			
10ZS2.25×105	0.13	1.05	1.54	0.99	1.11	1.26	0.99	0.85	1.09	1.10	1.14	0.93
-8	0.86	1.16	0.89	0.99	0.99	0.77	0.86	0.92	0.91	0.92	0.91	0.79
-4	1.00	1.18	0.90	0.95	0.79	0.86	1.07	0.92	0.82	0.92	0.92	0.82
0	1.38	1.39	1.00	1.00	1.00	1.00	1.00	1.39	1.00	1.00	1.00	1.00
4	1.30	1.66	1.14	1.30	0.95	1.18	1.44	1.20	1.04	1.20	1.20	1.04
8	1.14	1.59	1.17	1.33	0.88	1.11	1.32	1.23	0.97	1.23	1.23	0.97
11.711	1.08	1.84	1.18	1.55	0.85	1.27	1.23	1.26	0.94	1.26	1.26	0.94
12	1.07	1.83	1.19	1.56	0.85	1.27	1.22	1.26	0.94	1.26	1.26	0.94
16	0.98	1.84	1.21	1.64	0.83	1.25	1.15	1.29	0.92	1.29	1.29	0.92
20	0.91	1.86	1.23	1.74	0.82	1.25	1.10	1.33	0.91	1.33	1.33	0.91
90	0.13		0.99		0.99		0.99		0.99	0.99	0.99	0.99
6ZS2.25×105	0.37	1.09	1.72	1.02	1.21	1.62	1.02	1.00	1.41	1.22	1.32	1.13
-8	0.82	1.22	0.94	1.26	0.83	1.13	0.90	1.00	0.89	1.00	1.00	0.89
-4	0.92	1.13	0.94	1.08	0.86	1.01	1.01	1.00	0.92	1.00	1.00	0.92
0	1.19	1.23	1.04	1.07	1.04	1.07	1.21	1.06	1.06	1.06	1.06	1.06
4	1.26	1.69	1.23	1.53	1.08	1.42	1.52	1.41	1.28	1.52	1.52	1.28
8	1.19	1.93	1.24	1.79	1.02	1.58	1.49	1.46	1.24	1.49	1.49	1.24
12	1.13	1.95	1.27	1.86	1.01	1.55	1.46	1.50	1.22	1.50	1.50	1.22
16	1.17	2.51	1.34	2.42	1.04	1.94	1.44	1.55	1.22	1.55	1.55	1.22
20	1.15	2.49	1.38	2.47	1.05	1.88	1.42	1.60	1.22	1.60	1.60	1.22
23.481	1.13	2.50	1.41	2.52	1.07	1.84	1.40	1.63	1.23	1.63	1.63	1.23
90	0.37		1.02		1.02		1.02		1.02	1.02	1.02	1.02
Grand Total (Mean)	0.25	1.07	1.63	1.00	1.16	1.45	1.00	0.92	1.26	1.16	1.23	1.03
Grand Total (COV)	0.66	0.16	0.30	0.14	0.15	0.35	0.14	0.14	0.29	0.43	0.28	0.26

Classic simulation vs prediction plots:

In addition to Tables 10 and 11 the overall accuracy of the studied design methods is assessed in Fig. 23 and 24. The results show Method 3 to be the most accurate, and that for the stocky/low slenderness cases Methods 2 and 3 essentially converge. Although Method 1 appears reasonable in Fig. 23, when all cases are considered – as provided in Fig. 24 some extremely unconservative cases are revealed (see Table 10 or 11 for further details). Limitations on the applicability of Method 1 are clearly needed.

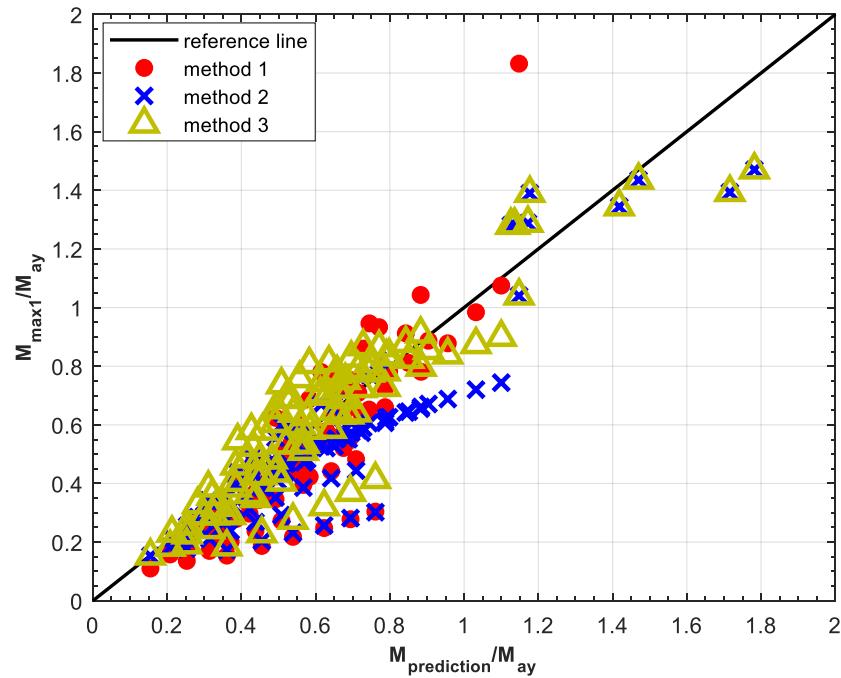


Figure 23. Simulation versus prediction for the three methods about all cases (With Range limitation).

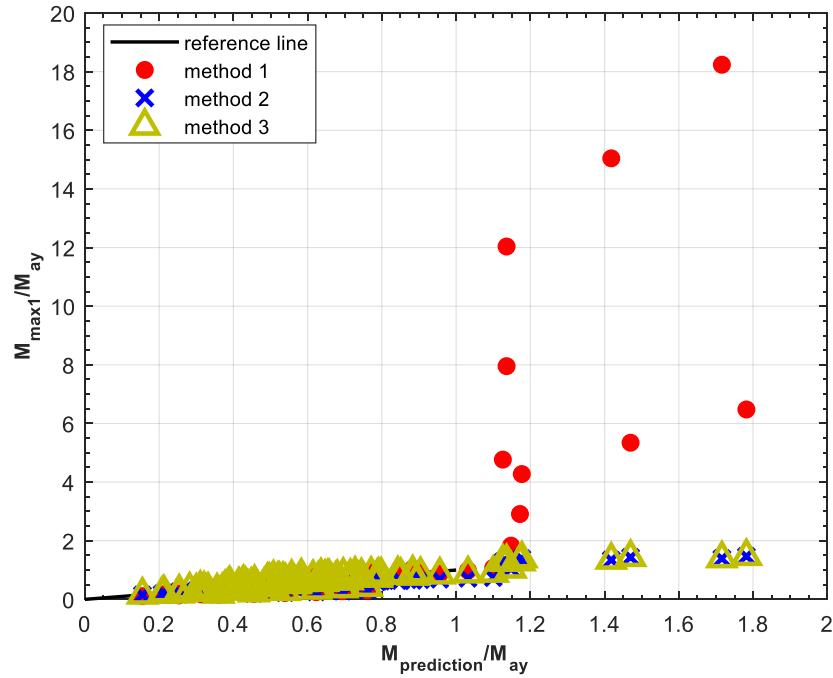


Figure 24. Simulation versus prediction for the three methods about all cases (Without range limitation).

λ_e vs strength:

Method 3 is essentially a variant of the Direct Strength Method. As such, the method can be compared in a classical slenderness vs. strength plot as provided in Fig. 25-28. Fig. 25 again shows the abnormally high strength from the slender 6ZS2.25x105 as it rotates and plastifies about its minor axis – with the removal of this data the overall good agreement of the approach is shown in Fig. 27 and 28.

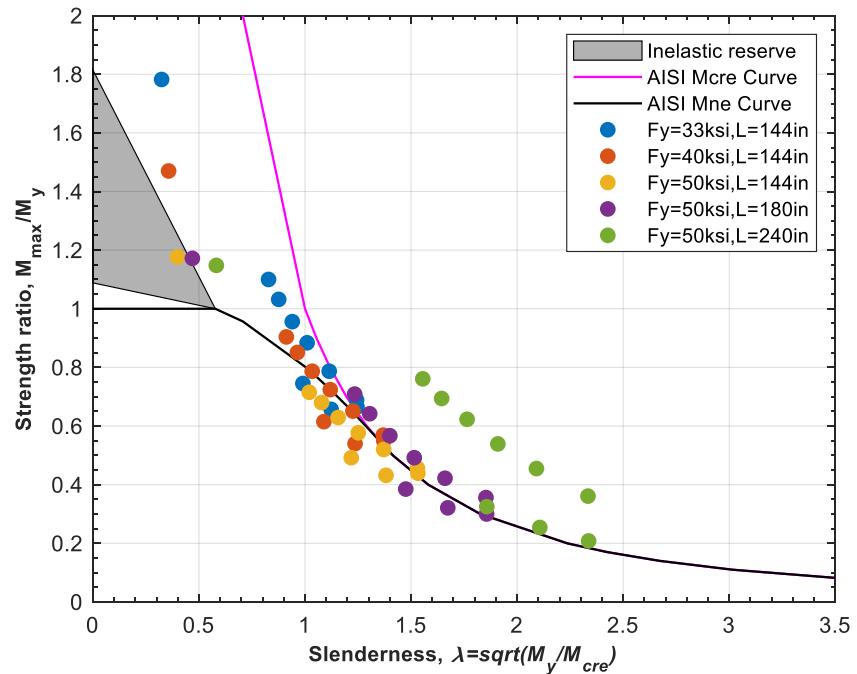


Figure 25. Strength ratio versus slenderness for 6ZS2.25×105 from ABAQUS collapse analysis.

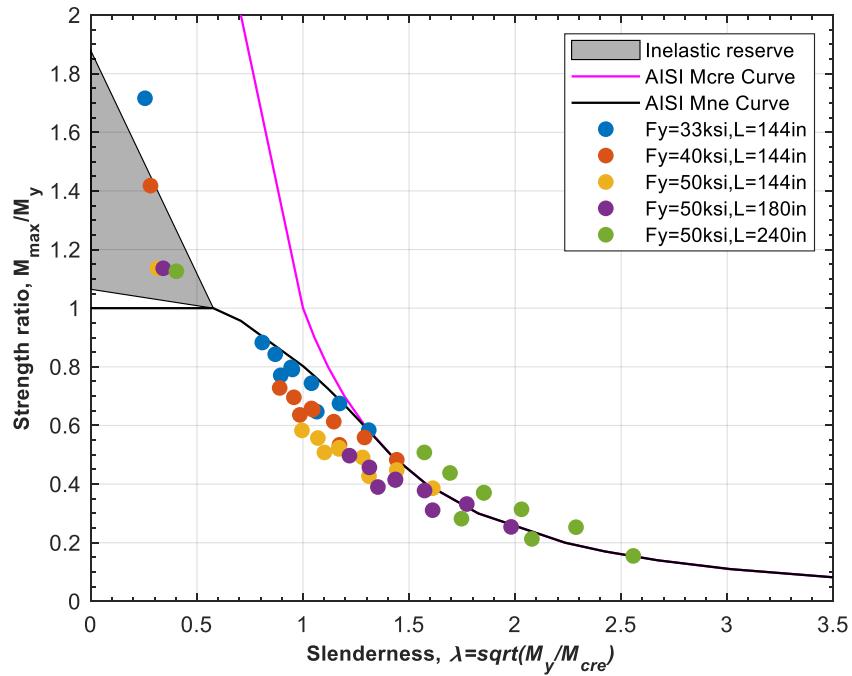


Figure 26. Strength ratio versus slenderness for 10ZS2.25×105 from ABAQUS collapse analysis.

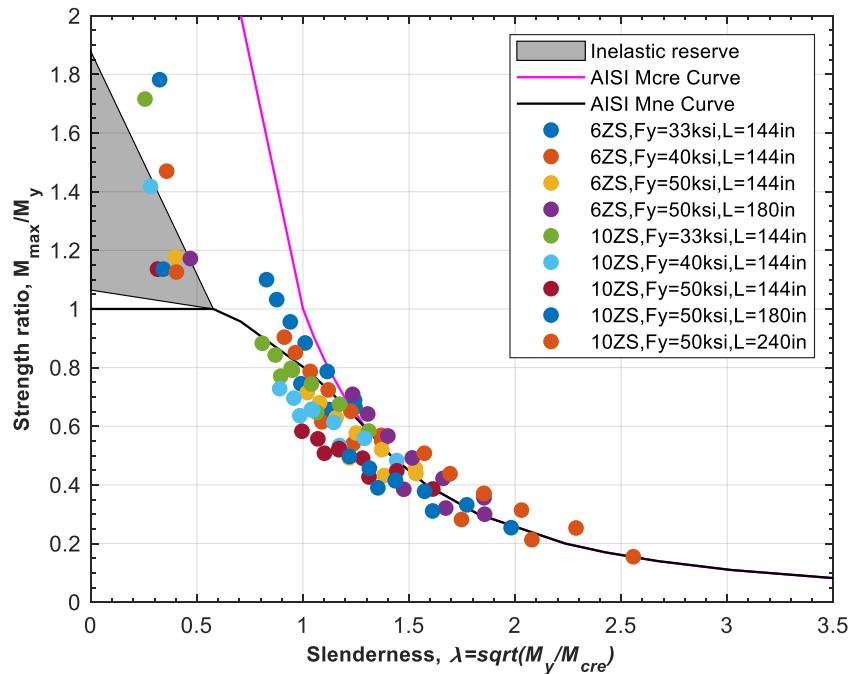


Figure 27. Strength ratio versus slenderness for all cases from ABAQUS collapse analysis (With case detail, excluding 6ZS2.25×105 with L = 240 inches).

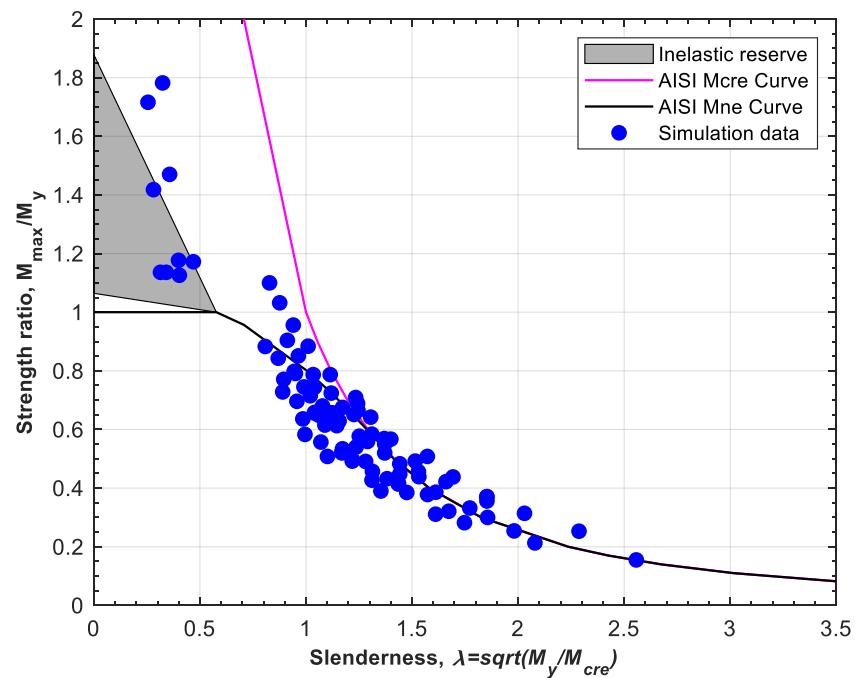


Figure 28. Strength ratio versus slenderness for all cases from ABAQUS collapse analysis
(Excluding 6ZS2.25×105 with L = 240 inches).

Interaction diagrams:

Method 2 uses an interaction equation approach to strength prediction, therefore directly examining the performance against the interaction equation in AISI provides a useful assessment of the method as shown in Fig. 29-32. Method 2 is consistently conservative. As the difference between Fig. 31 and Fig. 32 indicates including inelastic reserve in the strength prediction is important for accuracy.

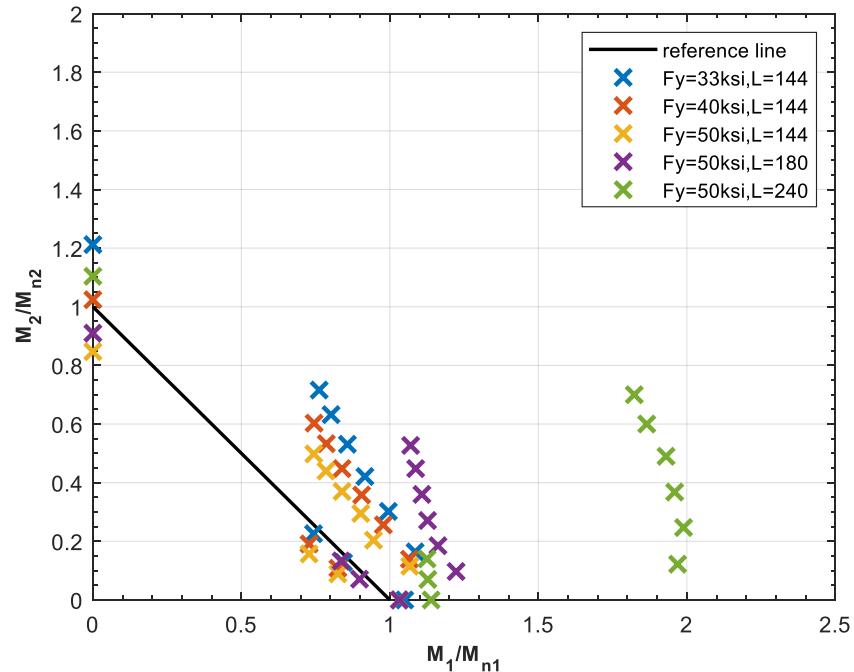


Figure 29. linear interaction for 6ZS2.25×105 (With inelastic reserve).

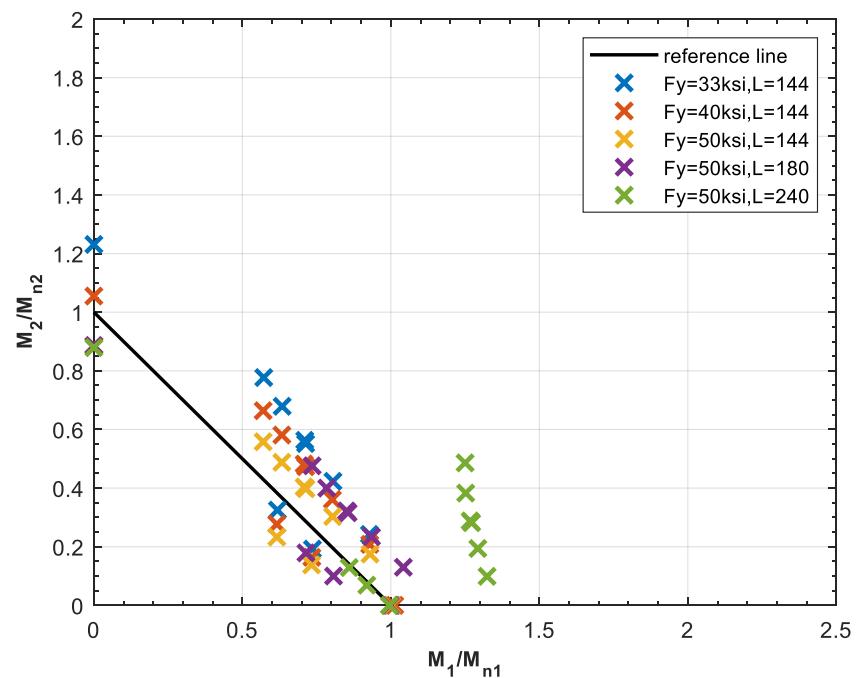


Figure 30. linear interaction for 10ZS2.25×105 (With inelastic reserve).

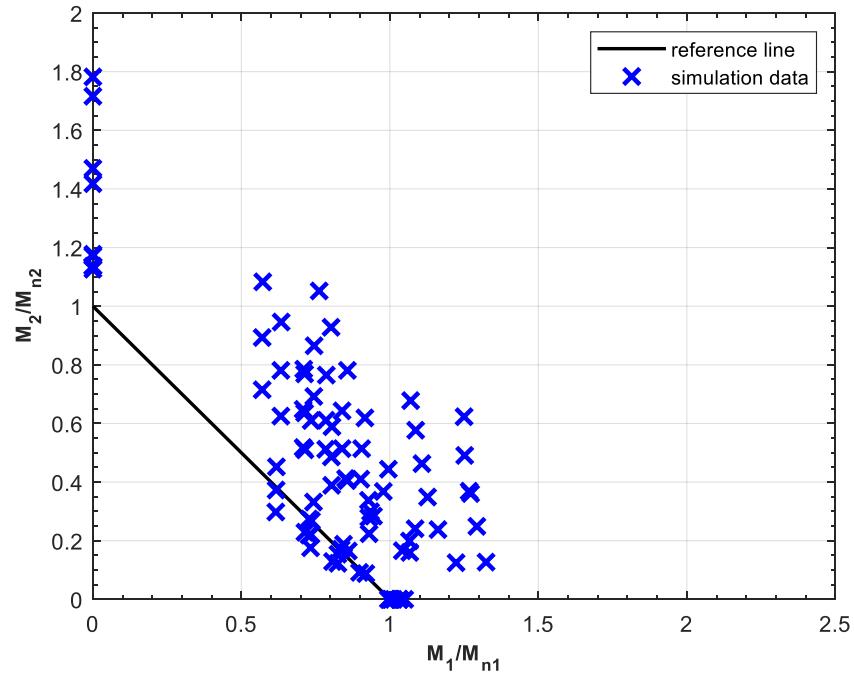


Figure 31. linear interaction for all cases (No inelastic reserve, exclude 6ZS2.25×105 with L = 240 inches).

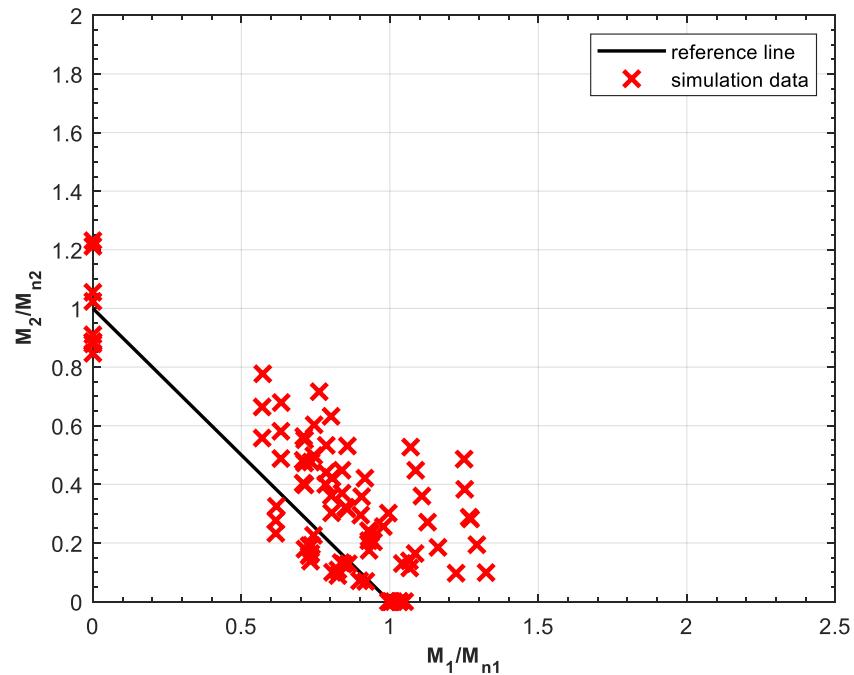


Figure 32. linear interaction for all cases (With inelastic reserve, exclude 6ZS2.25×105 with L = 240 inches).

Direct Bi-axial Bending diagrams:

Given that Method 2 is most naturally assessed through examination of the interaction expressions it may be insightful to view Method 3's predicted interaction expression – i.e. what does the prediction of Method 2 look like when plotted in the biaxial bending interaction space. Such plots are provided in Fig. 33 and 34. These curves indicate the significant improvement that Method 3 is able to make on the classic interaction expression – and provide further support for its recommendation as a primary method of strength prediction.

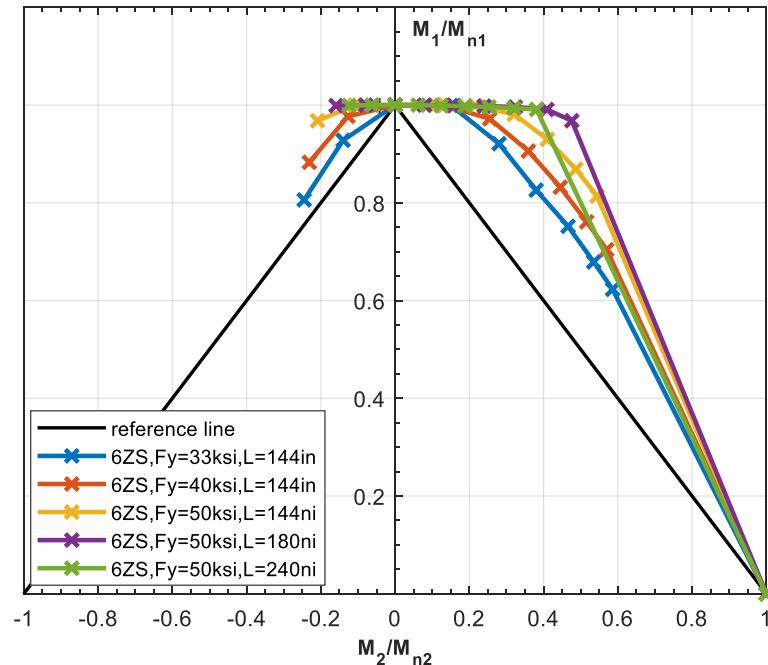


Figure 33. Method 3 compares with linear reference line for 6ZS2.25×105.

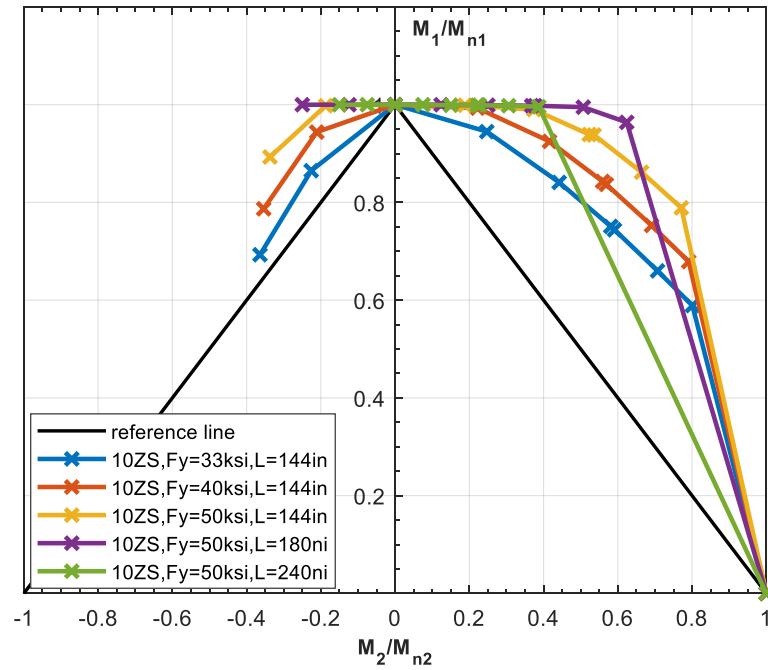


Figure 34. Method 3 compares with linear reference line for 10ZS2.25×105.

8 Conclusions

Applications for non-symmetric cold-formed steel members commonly induce biaxial bending since loads are almost never aligned with the principal axes of the section. Recently, Glauz (2017) developed an analytical solution for the lateral-torsional buckling (LTB) moment (M_{cre}) of a non-symmetric section bent about an arbitrary axis. These provisions could potentially replace simplified expressions used in AISI-S100-16 for M_{cre} ; however, the impact of applying this expression in design has not been fully assessed for LTB limit states.

To assess the implications of employing the more accurate M_{cre} solution a series of shell finite element collapse analyses were performed on two Zee-sections: 6ZS2.25×105 and 10ZS2.25×105, previously identified to be controlled by LTB, as opposed to local or distortional buckling. The collapse simulations were performed on sharp corner models of the Zee shapes under isolated and equal end moments and were augmented by eigenvalue buckling analysis in ABAQUS and finite strip method analyses conducted in CUFSM and in CFS. All of the ABAQUS shell finite element collapse simulations converged at large enough deformations to achieve at least one peak moment. After bifurcation and buckling, some of the longer studied members continued to rotate significantly, sometimes resulting in secondary peak moments – generally consistent with plastic bending capacity about the minor principal axis of the section.

Three design approaches were compared to the conducted simulations: (1) AISI-S100-16 approximate approach, (2) AISI-S100-16 interaction approach, and (3) direct bi-axial bending approach. For method 1, the AISI S100-16 approximate approach uses a conservatively low estimate of M_{cre} , but ignores bending about anything other than the geometric axis – this combination of conservative and unconservative assumptions balances out as long as the bending axis is reasonably close to the geometric axis – for large deviations it is problematic and invalid. For method 2, the AISI-S100-16 interaction approach uses the elastic buckling and strength about the major- and minor-principal axes as anchors and gives reasonable predictions, but can be overly conservative particularly if inelastic reserve is ignored. For method 3, the direct bi-axial bending approach is a rational extension of the Direct Strength Method and uses the buckling and yielding solutions about the arbitrary axis of bending - and is shown to provide the best overall prediction of the strength.

Many of the bi-axial bending finite element collapse simulations exhibited large rotations which would likely be deemed unacceptable in practice. Future study would be appropriate to estimate the rotation and establish serviceability limits or guidelines. In addition, this study did not assess the impact of moment gradient, nor that of local or distortional buckling for bending about arbitrary axes.

9 References

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ABAQUS (version 6.13)

10ZS2.25×105	50	144	8	1.281	Medium	0.491	0.323	1.141	1.107	0.812	0.430	0.444	0.605
10ZS2.25×105	50	144	11.711	1.170	Medium	0.524	0.337	1.028	1.112	0.761	0.510	0.471	0.689
10ZS2.25×105	50	144	12	1.169	Medium	0.520	0.339	1.020	1.112	0.755	0.510	0.467	0.689
10ZS2.25×105	50	144	16	1.070	Medium	0.557	0.359	0.925	1.120	0.735	0.602	0.497	0.758
10ZS2.25×105	50	144	20	0.995	Medium	0.583	0.382	0.846	1.128	0.723	0.688	0.517	0.806
10ZS2.25×105	50	144	90	0.314	Low	1.136	0.605	0.094	0.886	0.886	12.035	1.281	1.281
10ZS2.25×105	50	180	-8	1.353	Medium	0.390	0.284	0.958	0.892	0.714	0.407	0.437	0.546
10ZS2.25×105	50	180	-4	1.611	Slender	0.311	0.258	1.100	0.908	0.807	0.283	0.343	0.385
10ZS2.25×105	50	180	0	1.981	Slender	0.254	0.239	1.380	0.998	0.998	0.184	0.255	0.255
10ZS2.25×105	50	180	4	1.772	Slender	0.332	0.234	1.462	1.172	1.042	0.227	0.283	0.319
10ZS2.25×105	50	180	8	1.573	Slender	0.378	0.249	1.330	1.168	0.936	0.284	0.324	0.404
10ZS2.25×105	50	180	11.711	1.436	Medium	0.416	0.268	1.235	1.172	0.858	0.337	0.355	0.485
10ZS2.25×105	50	180	12	1.435	Medium	0.414	0.270	1.229	1.173	0.853	0.337	0.353	0.485
10ZS2.25×105	50	180	16	1.313	Medium	0.457	0.295	1.148	1.184	0.788	0.398	0.386	0.579
10ZS2.25×105	50	180	20	1.219	Medium	0.497	0.326	1.092	1.211	0.762	0.455	0.411	0.652
10ZS2.25×105	50	180	90	0.341	Low	1.136	0.605	0.143	0.886	0.886	7.955	1.281	1.281
10ZS2.25×105	50	240	-8	1.747	Slender	0.282	0.206	1.156	0.989	0.860	0.244	0.285	0.328
10ZS2.25×105	50	240	-4	2.079	Slender	0.213	0.176	1.254	0.987	0.919	0.170	0.215	0.231
10ZS2.25×105	50	240	0	2.557	Slender	0.155	0.145	1.401	1.012	1.012	0.110	0.153	0.153
10ZS2.25×105	50	240	4	2.287	Slender	0.253	0.178	1.860	1.423	1.324	0.136	0.178	0.191
10ZS2.25×105	50	240	8	2.030	Slender	0.314	0.207	1.843	1.488	1.294	0.170	0.211	0.243
10ZS2.25×105	50	240	11.711	1.853	Slender	0.371	0.239	1.837	1.554	1.274	0.202	0.239	0.291
10ZS2.25×105	50	240	12	1.852	Slender	0.370	0.241	1.832	1.555	1.269	0.202	0.238	0.292
10ZS2.25×105	50	240	16	1.693	Slender	0.438	0.282	1.837	1.636	1.255	0.238	0.268	0.349
10ZS2.25×105	50	240	20	1.572	Slender	0.508	0.333	1.862	1.736	1.255	0.273	0.292	0.405
10ZS2.25×105	50	240	90	0.403	Low	1.126	0.600	0.236	0.879	0.879	4.767	1.281	1.281



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